

Software Model Checking by Program Specialization

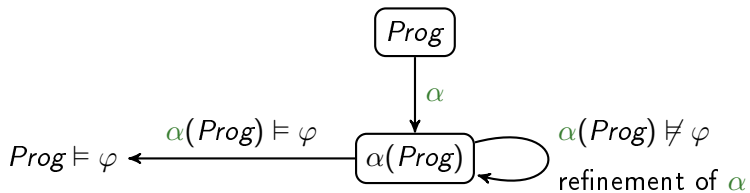
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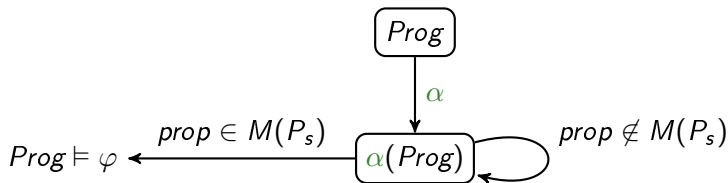
²CNR-IASI, Rome

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Software Model Checking



Software Model Checking by CLP Program Specialization



$Prog$ written in \mathcal{L} and φ specified in \mathcal{M}

Phase 1: Encode as a CLP program

$Prog \longrightarrow \alpha(Prog)$

$\mathcal{L} \longrightarrow I$, interpreter for \mathcal{L}

$\varphi \longrightarrow prop$

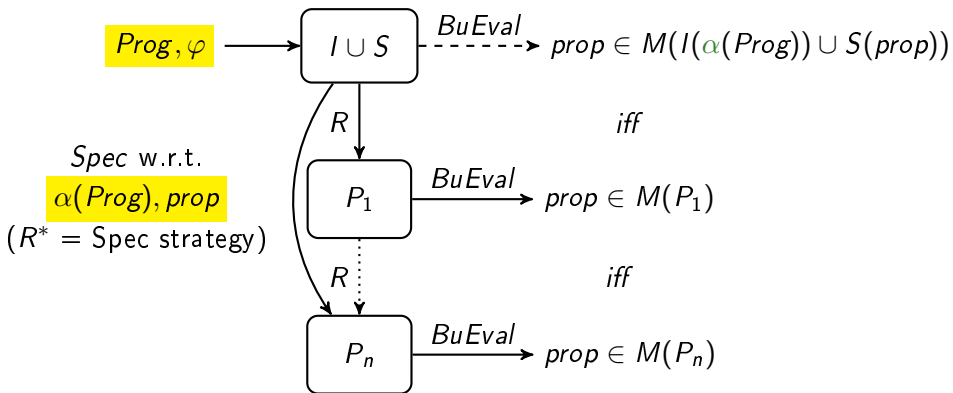
$\mathcal{M} \longrightarrow S$, interpreter for \mathcal{M}

Phase 2: *Spec* - Specialize I and S w.r.t. $\alpha(Prog)$ and $prop \longrightarrow P_s$

Phase 3: *BuEval* - Bottom up Evaluation of $M(P_s)$

$Prog \models \varphi$ iff $prop \in M(I(\alpha(Prog)) \cup S(prop))$ iff $prop \in M(P_s)$.

Rule-based CLP Program Specialization



$R \in \{\text{Unfolding, Folding, Clause Removal, Definition introduction}\}$

R1 - Unfolding

$p(X_1, \dots, X_n) \leftarrow c \wedge q(X_1, \dots, X_n)$ w.r.t. $q(X_1, \dots, X_n) \leftarrow d \wedge A$

gives

$p(X_1, \dots, X_n) \leftarrow c \wedge d \wedge A$

$$P_i = \left\{ \begin{array}{l} q(X) \leftarrow Y = X + 1 \wedge r(Y) \\ q(X) \leftarrow s(X) \\ p(X) \leftarrow q(X) \end{array} \right\}$$

$\xrightarrow[p \text{ w.r.t. } q]{R1}$

$$P_{i+1} = \left\{ \begin{array}{l} q(X) \leftarrow Y = X + 1 \wedge r(Y) \\ q(X) \leftarrow s(X) \\ p(X) \leftarrow Y = X + 1 \wedge r(Y) \\ p(X) \leftarrow s(X) \end{array} \right\}$$

R2 - Folding

$p(X_1, \dots, X_n) \leftarrow c \wedge A$ w.r.t. A by using $q(X_1, \dots, X_n) \leftarrow d \wedge A$
gives

$p(X_1, \dots, X_n) \leftarrow c \wedge q(X_1, \dots, X_n)$ if $c \Rightarrow d$

$$\begin{array}{ccc} P_i = \{ & \xrightarrow{\text{R2}} & P_{i+1} = \{ \\ \quad q(Y) \leftarrow Y \geq 0 \wedge r(Y) & & \quad q(X) \leftarrow Y = X + 1 \wedge r(Y) \\ \quad p(X) \leftarrow Y = X + 1 \wedge Y = 0 \wedge r(Y) & \text{p w.r.t. } r, s & \quad p(X) \leftarrow Y = X + 1 \wedge Y = 0 \wedge q(X) \\ \} & \text{by using } q & \} \end{array}$$

R3 - Clause removal

R3.1 $p(X_1, \dots, X_n) \leftarrow c \wedge q(X_1, \dots, X_n)$ if c is unsatisfiable

R3.2 $p(X_1, \dots, X_n) \leftarrow c \wedge q(X_1, \dots, X_n),$
 $p(X_1, \dots, X_n) \leftarrow d$ if $c \rightarrow d$ (subsumption)

$$P_i = \left\{ \begin{array}{l} q(X) \leftarrow Y = X + 1, Y < X \wedge r(Y) \\ p(X) \leftarrow X > 0 \wedge r(X) \\ p(X) \leftarrow r(X) \end{array} \right\}$$

$\xrightarrow{R3}$

$$P_{i+1} = \left\{ \begin{array}{l} q(X) \leftarrow Y = X + 1, Y < X \wedge r(Y) \\ p(X) \leftarrow X > 0 \wedge r(X) \\ p(X) \leftarrow r(X) \end{array} \right\}$$

R4 - Definition introduction

$$\text{newp}(X_1, \dots, X_n) \leftarrow c \wedge A$$

$$P_i = \left\{ \begin{array}{l} q(X) \leftarrow Y = X + 1 \wedge r(Y) \\ q(X) \leftarrow s(X) \\ p(X) \leftarrow q(X) \end{array} \right\}$$

$\xrightarrow{R4}$

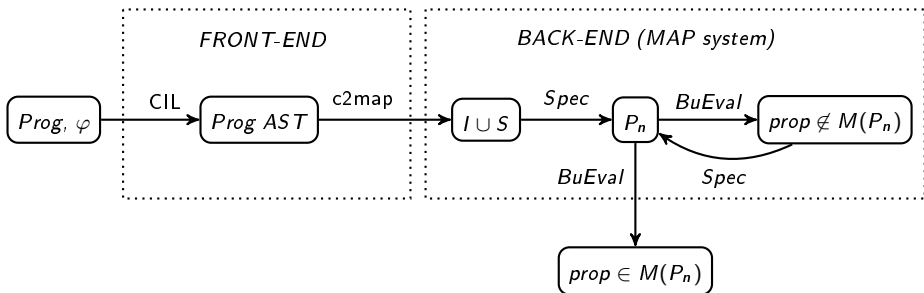
$$P_{i+1} = \left\{ \begin{array}{l} q(X) \leftarrow Y = X + 1 \wedge r(Y) \\ q(X) \leftarrow s(X) \\ p(X) \leftarrow Y = X + 1 \wedge r(Y) \\ \text{newp}(X) \leftarrow p(X) \wedge r(X) \end{array} \right\}$$

Specialization strategy

```
Spec( $P, c$ ) {  
   $P_s = \emptyset$ ;  
   $Def = \{c\}$ ;  
  while  $\exists q \in Def$  do  
     $Unf = \text{Clause Removal}(\text{Unfold}(q))$ ;  
     $Def = (Def - \{q\}) \cup \text{Define}(Unf)$ ;  
     $P_s = P_s \cup \text{Fold}(Unf, Def)$   
  done  
}
```

$prop \in M(P)$ iff $prop \in M(P_s)$

Software Model Checker Architecture - C programs



CIL front-end:

<http://http://kerneis.github.com/cil/>

by Necula et al.

MAP system:

<http://www.iasi.cnr.it/~proietti/system.html>

by the MAP group

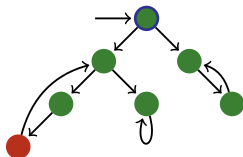
Safety checking of C programs

Phase 1: $\mathcal{M} \rightarrow S, \varphi \rightarrow prop$

$$\mathcal{M} \rightarrow S = \begin{cases} \text{ureach}(X) \text{ :- unsafe}(X). \\ \text{ureach}(X) \text{ :- t}(X, X'), \text{ ureach}(X'). \\ \text{unsafe} \text{ :- initial}(X), \text{ ureach}(X). \\ \text{unsafe}(\text{cf}(\text{error}, E)). \\ \text{initial}(\text{cf}(\text{call}(\text{main}, [], \text{id}(\text{undef}), \text{halt}), E)). \end{cases}$$

$\varphi \rightarrow prop = \text{safe} \text{ :- not unsafe.}$

○



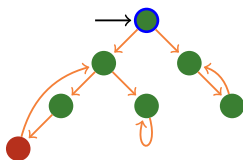
Safety checking of C programs

Phase 1: $\mathcal{M} \rightarrow S, \varphi \rightarrow prop$

$$\mathcal{M} \rightarrow S = \begin{cases} \text{ureach}(X) \text{ :- } \text{unsafe}(X). \\ \text{ureach}(X) \text{ :- } \boxed{\text{t}(X, X')}, \text{ureach}(X'). \\ \text{unsafe} \text{ :- } \text{initial}(X), \text{ureach}(X). \\ \text{unsafe}(\text{cf}(\text{error}, E)). \\ \text{initial}(\text{cf}(\text{call}(\text{main}, [], \text{id}(\text{undef}), \text{halt}), E)). \end{cases}$$

$\varphi \rightarrow prop = \text{safe} \text{ :- } \text{not unsafe}.$

○



Safety checking of C programs

Phase 1: $\mathcal{L} \rightarrow I, \text{Prog} \rightarrow \alpha(\text{Prog})$

$$\mathcal{L} \rightarrow I = \left\{ \begin{array}{l} \mathbf{t}(\mathbf{cf}(\mathbf{asgn}(\mathbf{ID}, \mathbf{E}, \mathbf{L}), \mathbf{S}), \mathbf{cf}(\mathbf{C}, \mathbf{S1})) \text{ :-} \\ \quad \mathbf{aeval}(\mathbf{E}, \mathbf{S}, \mathbf{V}), \mathbf{update}(\mathbf{ID}, \mathbf{V}, \mathbf{S}, \mathbf{S1}), \mathbf{cmd}(\mathbf{L}, \mathbf{C}). \text{ \%ID=E} \\ \mathbf{t}(\mathbf{cf}(\mathbf{ite}(\mathbf{E}, \mathbf{L1}, _), \mathbf{S}), \mathbf{cf}(\mathbf{C}, \mathbf{S})) \text{ :-} \\ \quad \mathbf{beval}(\mathbf{E}, \mathbf{S}), \mathbf{cmd}(\mathbf{L}, \mathbf{C}). \quad \quad \quad \text{\% if(E) { L1 }} \\ \mathbf{t}(\mathbf{cf}(\mathbf{ite}(\mathbf{E}, _, \mathbf{L2}), \mathbf{S}), \mathbf{cf}(\mathbf{C}, \mathbf{S})) \text{ :-} \\ \quad \mathbf{beval}(\mathbf{not}(\mathbf{E}), \mathbf{S}), \mathbf{cmd}(\mathbf{L2}, \mathbf{C}). \quad \quad \quad \text{\% else{ L2 }} \\ \mathbf{t}(\mathbf{cf}(\mathbf{goto}(\mathbf{L}), \mathbf{S}), \mathbf{cf}(\mathbf{C}, \mathbf{S})) \text{ :- } \mathbf{cmd}(\mathbf{L}, \mathbf{C}). \quad \text{\% goto(L)} \\ \mathbf{t}(\mathbf{cf}(\mathbf{call}(\mathbf{F}, \mathbf{ArgL}, \mathbf{OID}, \mathbf{Ret}), \mathbf{S}), \mathbf{cf}(\mathbf{goto}(\mathbf{Ep}), \mathbf{S1})) \text{ :-} \\ \quad \mathbf{prologue}(\mathbf{F}, \mathbf{ArgL}, \mathbf{S}, \mathbf{OID}, \mathbf{Ret}, \mathbf{Ep}, \mathbf{S1}). \\ \mathbf{t}(\mathbf{cf}(\mathbf{ret}(\mathbf{E}), \mathbf{S}), \mathbf{cf}(\mathbf{C}, \mathbf{S1})) \text{ :-} \\ \quad \mathbf{epilogue}(\mathbf{E}, \mathbf{S}, \mathbf{S1}, \mathbf{Ret}), \mathbf{cmd}(\mathbf{Ret}, \mathbf{C}). \end{array} \right.$$

Safety checking of C programs

Phase 2: *Spec* - Specialize $P_0 = I \cup S \cup \alpha Prog$ w.r.t. *initial*

$$\text{Spec}(P_0, \text{initial}) = P_n$$

Phase 3: *BuEval* - Bottom up Evaluation of $M(P_n)$

Prog is *safe* iff *unsafe* $\notin M(P_0)$ iff *unsafe* $\notin M(P_n)$.

Example

Phase 1: from C to CIL

```
int main()
{
    int x=0;
    int y=0;
    int n;

    while (x<n) {
        x = x + 1;
        y = y + 1;
    }

    if (y>x)
        goto ERROR;

    return 0;
}
```

```
int main(void) {
    int x ; int y ; int n ;
    int x=0;
    int y=0;

    while (1) {
        while_continue: ;
        if (x<n) { }
        else { goto while_break; }
        x = x + 1;
        y = y + 1;
    }
    while_break: ;

    if (y>x)
        goto ERROR;
    return (0);
}
```

Example

Phase 1: from CIL to CLP

```
int main()
{
  x=0;          cmd(l0,asgn(id(x),aexp(const(0))),l1)).
  y=0;          cmd(l1,asgn(id(y),aexp(const(0))),l2)).
  while (1) {
    if (x<n) { } cmd(l2,ite(bexp(lt(aexp(id(x))),aexp(id(n))))),l3,l5)).
    else { goto while_break; }
    x = x + 1;   cmd(l3,asgn(id(x),aexp(plus(aexp(id(x))),aexp(const(1))))),l4)).
    y = y + 1;   cmd(l4,asgn(id(y),aexp(plus(aexp(id(y))),aexp(const(1))))),l2)).
  }
}
if (y>x)       cmd(l5,ite(bexp(gt(aexp(id(y))),aexp(id(x))))),l6,l7)).
  goto ERROR;  cmd(l6,error).

return 0;      cmd(l7,ret(aexp(const(0)))).
}
```


Example

Phase 2

```
int main(void) {
    int x ; int y ; int n ;
    int x=0; int y=0;

    while (1) {
        while_continue:    ;
        if (x<n) { } else { goto while_break; }
        x = x + 1; y = y + 1;
    }
    while_break:    ;

    if (y>x) goto ERROR;
    return (0);
}

unsafe :- X=0, Y=0, N>=1, new1(X,Y,N).
new1(X,Y,N) :- X<N, X'=X+1, Y'=Y+1, new1(X',Y',N).
new1(X,Y,N) :- X>=N, Y>X.
```

Example

Phase 3

```
unsafe :- X=0, Y=0, 1=<N, new1(X,Y,N).  
new1(X,Y,N) :- X<N, X'=X+1, Y'=Y+1, new1(X',Y',N).  
new1(X,Y,N) :- X>=N, Y>X.
```

↓ BuEval

```
{  
  new1(X,Y,N) :- Y>X, X>=N.  
  new1(X,Y,N) :- Y>X, N=X+1. %X+1=<N, X'=X+1, Y'=Y+1, X'>=N, Y'>X  
  new1(X,Y,N) :- Y>X, N=X+2.  
  new1(X,Y,N) :- Y>X, N=X+3.  
  . . . .  
}
```

BuEval diverges.

Unable to prove *Prog* safe.

Example

Phase 2

```
unsafe :- X=0, Y=0, N>=1, new1(X,Y,N).
```

```
new1(X,Y,N) :- N>=X+1, X'=X+1, Y'=Y+1, new1(X',Y',N).
```

```
new1(X,Y,N) :- N<X, X+1=<Y.
```

↓ Spec

```
unsafe :- X=0, Y=0, N>=1, new1(X,Y,N).
```

```
new2(X,Y,N) :- N>=X, X'=X+1, Y'=Y+1, X'>=Y', Y'>=1, new2(X',Y',N).
```

```
new1(X,Y,N) :- X=0, Y=0, N>=1, Y'=1, X'=1, new2(X',Y',N).
```

No facts

BuEval terminates

Prog is safe!

Preliminary results

Simple IMPerative language $SIMP \subset C$

Programs	ARMC	TRACER	MAP
<i>f1a</i>	∞	\perp	0.08
<i>f2</i>	∞	\perp	7.58
<i>Substring</i>	719.39	180.09	10.20
<i>prog_dagger</i>	∞	\perp	5.37
<i>seesaw</i>	3.41	\perp	0.03
<i>tracer_prog_d</i>	∞	0.01	0.03
<i>interpolants_needed</i>	0.13	\perp	0.06
<i>widen_needed</i>	∞	\perp	0.07

Real world C programs (e.g. Device drivers)