

Software Model Checking by Program Specialization

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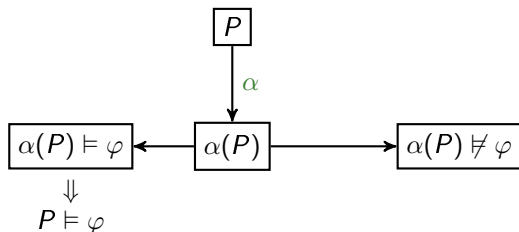
³CNR-IASI, Rome

CILC 2012

Rome, 6 June 2012

Software model checking

- ▶ given:
 1. a **program** P
 2. a **formal specification** φ of its behaviour
- ▶ create a conservative **abstraction** $\alpha(P)$ of P
- ▶ verify whether or not $\alpha(P)$ satisfies φ

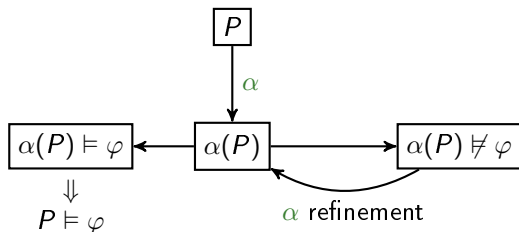


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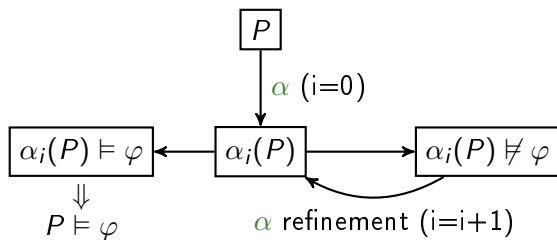
Software model checking

Modelling software

abstraction $\alpha(P)$:

- ▶ must be **sound**: if $\alpha(P) \models \varphi$ then $P \models \varphi$
- ▶ should be as **precise** as possible

$$\alpha_1(P) \sqsubseteq \alpha_2(P) \sqsubseteq \dots \sqsubseteq \alpha_i(P) \sqsubseteq \dots$$



Program Specialization

Program specialization is a transformation technique whose objective is the **adaptation** of a program to a **context of use**.

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Program specialization is a framework for performing an **Agile**, **Iterative** and **Evolutionary** development of verification techniques and tools:

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- ▶ **compositionality** of program transformations

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- ▶ **soundness** of abstraction
- ▶ **parametricity** w.r.t. languages and logics
- ▶ **compositionality** of program transformations
- ▶ **modularity** separation of language features and verification techniques

Specialization-based Software Model Checking

Verification Framework

Given:

- ▶ a program P written in a language L , and
- ▶ a property φ in a logic M ,

we can verify that φ holds for P by:

Phase 1: writing an interpreter I for L and a semantics S for M in Constraint Logic Programming,

Phase 2: creating a model of P by specializing the interpreter I and the semantics S with respect to P and φ , and

Phase 3: analyzing the specialized program
(by, possibly, repeating Phase 2).

Peralta et al. *Analysis of Imperative Programs through Analysis of Constraint Logic Programs*.

Specialization-based Software Model Checking

Rules for Specializing CLP Programs

R1 Definition

R2 Unfolding

R3 Folding

R4 Clause removal

Specialization-based Software Model Checking

Rules for Specializing CLP Programs

R1 Definition $newp(X_1, \dots, X_n) \leftarrow c \wedge A$

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Specialization-based Software Model Checking

Rules for Specializing CLP Programs

R1 Definition $newp(X_1, \dots, X_n) \leftarrow c \wedge A$

R2 Unfolding $p(X_1, \dots, X_n) \leftarrow c \wedge q(X_1, \dots, X_n)$ w.r.t.

$$q(X_1, \dots, X_n) \leftarrow d \wedge A$$

gives

$$p(X_1, \dots, X_n) \leftarrow c \wedge d \wedge A$$

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R3 Folding $p(X_1, \dots, X_n) \leftarrow c \wedge A$ w.r.t. A by using

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gives

$$p(X_1, \dots, X_n) \leftarrow c \wedge q(X_1, \dots, X_n) \quad \text{if } c \Rightarrow d$$

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R4 Clause removal

R4.1 $p(X_1, \dots, X_n) \leftarrow c \wedge q(X_1, \dots, X_n)$

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R4 Clause removal

R4.1 $p(X_1, \dots, X_n) \leftarrow c \wedge q(X_1, \dots, X_n)$ if c is unsatisfiable

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R4.1 $p(X_1, \dots, X_n) \leftarrow \cancel{c} \wedge \cancel{q(X_1, \dots, X_n)}$ if c is unsatisfiable

R4.2 $p(X_1, \dots, X_n) \leftarrow \cancel{c} \wedge \cancel{q(X_1, \dots, X_n)}, p(X_1, \dots, X_n) \leftarrow d$

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R4.2 $\cancel{p(X_1, \dots, X_n) \leftarrow c \wedge q(X_1, \dots, X_n)}$, $p(X_1, \dots, X_n) \leftarrow d$

if $c \rightarrow d$ (subsumption)

Software model checking

Specialization strategy

$\text{Spec}(\Pi, c)$ **begin**

$\Pi_{Sp} = \emptyset;$

$\text{Def} = \{c\};$

while $\exists q \in \text{Def}$ **do**

$\text{Unf} = \text{Clause Removal}(\text{Unfold}(q));$

$\text{Def} = \text{Def} - \{q\} \cup \text{Define}(\text{Unf});$

$\Pi_{Sp} = \Pi_{Sp} \cup \text{Fold}(\text{Unf}, \text{Def})$

done

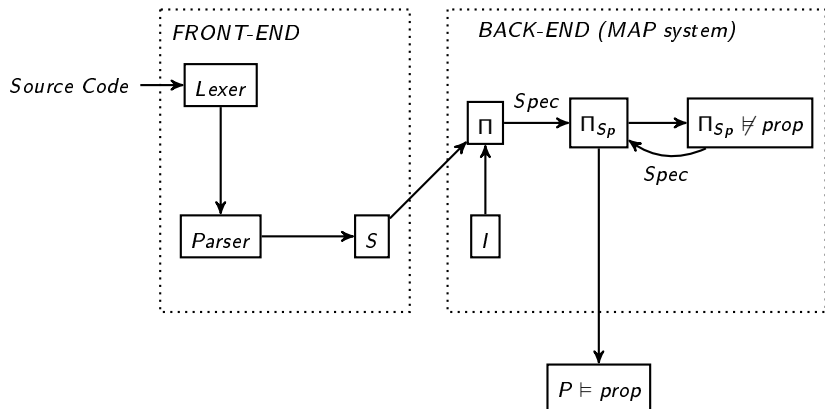
end

Theorem: $\Pi \models \varphi$ iff $\Pi_{Sp} \models \varphi$

- Generalizations in $\text{Define}(\cdot)$ ensure termination of Spec , but may prevent the proof of the property.

Software model checking

Framework Architecture



P and φ are encoded as S and $prop$, respectively.

Specialization-based Software Model Checking

Verification Framework: SIMP language and safety properties

$a ::= n \mid x \mid a_1 + a_2 \mid a_1 - a_2 \mid a_1 \times a_2$
 $b ::= \mathbf{true} \mid \mathbf{false} \mid a_1 \text{ op } a_2 \mid !b \mid b_1 \ \&\& \ b_2 \mid b_1 \ \|\ b_2$
 $t ::= \mathit{ndc} \mid b$
 $c ::= \mathit{skip} \mid x = a \mid c_1; c_2 \mid \mathbf{if } t \mathbf{ then } c_1 \mathbf{ else } c_2 \mid \mathbf{while } t \mathbf{ do } c \mathbf{ od}$

CLP interpreter for the operational semantics of SIMP

$\text{tr}(s(\text{skip}, S), E).$
 $\text{tr}(s(\text{asgn}(\text{var}(X), A), E), s(\text{skip}, E1)) \text{ :- aeval}(A, S, V), \text{update}(\text{var}(X), V, S, E1).$
 $\text{tr}(s(\text{comp}(C0, C1), S), s(C1, S1)) \text{ :- tr}(s(C0, S), S1).$
 $\text{tr}(s(\text{comp}(C0, C1), S), s(\text{comp}(C0', C1), S')) \text{ :- tr}(s(C0, S), s(C0', S')).$
 $\text{tr}(s(\text{ite}(B, C0, _), S), s(C0, S)) \text{ :- beval}(B, S).$
 $\text{tr}(s(\text{ite}(B, _, C1), S), s(C1, S)) \text{ :- beval}(\text{not}(B), S).$
 $\text{tr}(s(\text{ite}(\text{ndc}, S1, _), E), s(S1, E)).$
 $\text{tr}(s(\text{ite}(\text{ndc}, _, S2), E), s(S2, E)).$
 $\text{tr}(s(\text{while}(B, C), S), s(\text{ite}(B, \text{comp}(C, \text{while}(B, C)), \text{skip}), S)).$

Specialization-based Software Model Checking

Verification Framework: SIMP language and safety properties

Let P be a SIMP program and φ be a safety property.

- ▶ **Phase 1:** Encode P and φ into a CLP program Π

```
reachable(X) :- unsafe(X).  
reachable(X) :- tr(X,X'), reachable(X').  
unsafe :- initial(X), reachable(X).  
unsafe(s(error,E)).  
initial(s(T,E)) :- init_constraint(E).
```

where:

- ▶ $\text{tr}(X,X')$ encodes the operational semantics I of SIMP.
- ▶ $\text{s}(T,E)$ encodes P (instructions T and variables E)
- ▶ **Phase 2:** *Spec* - Specialize Π w.r.t.
 $\text{initial}(s(P,E)) \text{ :- init_constraint}(E).$
- ▶ **Phase 3:** *BuEval* - Bottom up Evaluation of Π_{Sp}

P is safe iff $\text{unsafe} \notin \text{BuEval}(\Pi)$ iff $\text{unsafe} \notin \text{BuEval}(\Pi_{Sp}).$

Example

Phase 1: Encoding of P and φ

```
int x=0; int y=0; int n;  
assume(n>0);  
while (x<n) { x = x+1; y = y+1; }  
if (y>x) error;
```



1. initial(
 s(comp(while(lt(var(x),var(n)),
 comp(asgn(var(x),plus(var(x),int(1))),
 asgn(var(y),plus(var(y),int(1))))),
 ite(gt(var(y),var(x)),error,skip))),
 [lv(x,X),lv(y,Y),lv(n,N)]) :- X=0,Y=0,N>0.
2. unsafe(s(error,_)).

Example

Phase 2: Specialization of I w.r.t. P

1. `initial(s(comp(while(···),···),[lv(x,X),···])) :- X=0,···,N>0.`
2. `unsafe(s(error,_)).`

+

3. CLP Interpreter



```
new1(X,Y,N) :- X+1=<N, X'=X+1, Y'=Y+1, new1(X',Y',N).
new1(X,Y,N) :- N=<X, Y>X.
unsafe :- X=0, Y=0, N>=1, new1(X,Y,N).
safe :- not unsafe.
```

$X+1=<N$



`while` $\xrightarrow{N=<X, Y>X}$ `error`

Example

Phase 3: Bottom Up Evaluation of the Specialized Program

Let Π_{Sp} the specialized CLP program:

```
new1(X,Y,N) :- N>=X+1, X'=X+1, Y'=Y+1, new1(X',Y',N).
```

```
new1(X,Y,N) :- N=<X, Y>=X+1.
```

```
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```

```
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```

$BuEval(\Pi_{Sp}) = \{$

```
new1(X,Y,N) :- X+1=<Y, N=<X.
```

```
new1(X,Y,N) :- X+1=<Y, N=X+1.
```

```
new1(X,Y,N) :- X+1=<Y, N=X+2.
```

```
new1(X,Y,N) :- X+1=<Y, N=X+3.
```

```
new1(X,Y,N) :- X+1=<Y, N=X+4.
```

```
..... }
```

Example

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The Bottom Up Evaluation does not terminate.

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```
new1(X,Y,N) :- X+1=<Y, N=X+4.
```

```
.... }
```

The Bottom Up Evaluation does not terminate.

Thus, we are not able to prove, or disprove, the safety of the given imperative program!

Example

Phase 2: Specialization of Π_{S_p}

```
new1(X,Y,N) :- N>=X+1, X'=X+1, Y'=Y+1, new1(X',Y',N).  
new1(X,Y,N) :- N=<X, X+1=<Y.  
unsafe :- X=0, Y=0, N>=1, new1(X,Y,N).  
safe :- not unsafe.
```



```
new2(X,Y,N) :- N>=X, X'=X+1, Y'=Y+1, X'>=Y', Y'>=1, new2(X',Y',N).  
new1(X,Y,N) :- X=0, Y=0, N>=1, Y'=1, X'=1, new2(X',Y',N).  
unsafe :- X=0, Y=0, N>=1, new1(X,Y,N).  
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No facts

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The Bottom Up Evaluation terminates

Example

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unsafe :- X=0, Y=0, N>=1, new1(X,Y,N).  
safe :- not unsafe.
```

No facts

The Bottom Up Evaluation terminates

Thus, the given imperative program is proved to be **safe!**

Experiments

Time (in seconds) taken for performing model checking.

\perp denotes 'terminating with error' (TRACER, using the default options, terminates with 'Fatal Error: Heap overflow').

∞ means 'Model checking not successful within 20 minutes'.

Programs	ARMC	TRACER	MAP
<i>f1a</i>	∞	\perp	0.08
<i>f2</i>	∞	\perp	7.58
<i>Substring</i>	719.39	180.09	10.20
<i>prog_dagger</i>	∞	\perp	5.37
<i>seesaw</i>	3.41	\perp	0.03
<i>tracer_prog_d</i>	∞	0.01	0.03
<i>interpolants_needed</i>	0.13	\perp	0.06
<i>widen_needed</i>	∞	\perp	0.07

Jaffar et al. *TRACER: A Symbolic Execution Tool for Verification*.

Podelski and Rybalchenko. *ARMC: The Logical Choice for Software Model Checking with Abstraction Refinement*.

Conclusions

- ▶ Program specialization is a suitable framework for defining verification procedures which are parametric w.r.t. the languages of
 - ▶ the program, and
 - ▶ the propertyto be verified
- ▶ Preliminary results show that this approach is also viable in practice and competitive with other CLP-based software model checkers
- ▶ We are extending the verification framework with
 - ▶ more sophisticated language features of imperative language (e.g., pointers, function calls);
 - ▶ different properties (e.g., content-sensitive properties)