

CARET analysis of multithreaded programs

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Malware detection is a big challenge.

Existing Techniques (not robust)

- Signature-matching based technique: can easily be overcome by obfuscation techniques
- Code emulation based techniques: limitation in execution time

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Solution to have a robust technique

Model-checking for malware detection

- allow us to analyse the behaviors (not the syntax) of the program without executing it

Binary Codes

Model-checking for Malware Detection

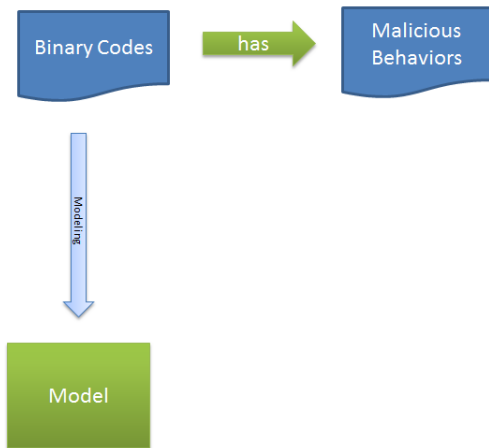
Binary Codes

Malicious
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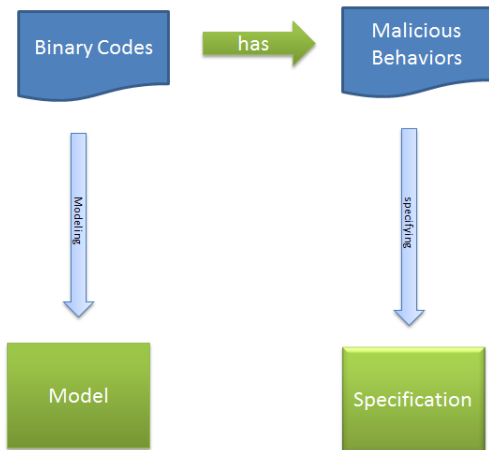
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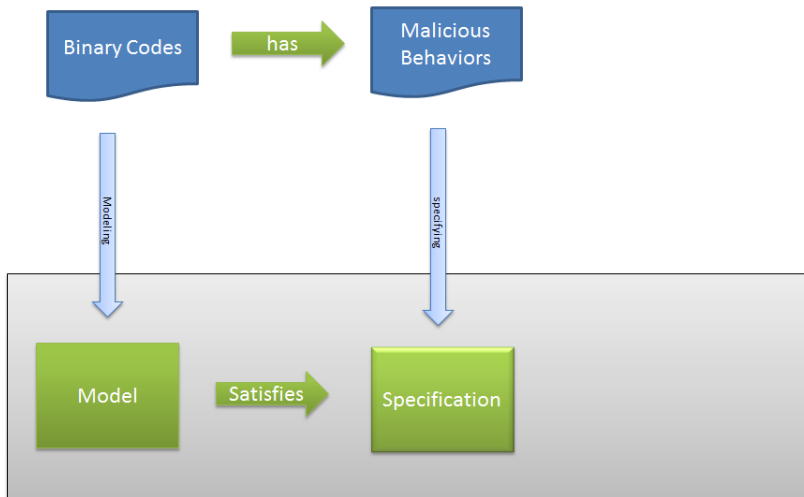
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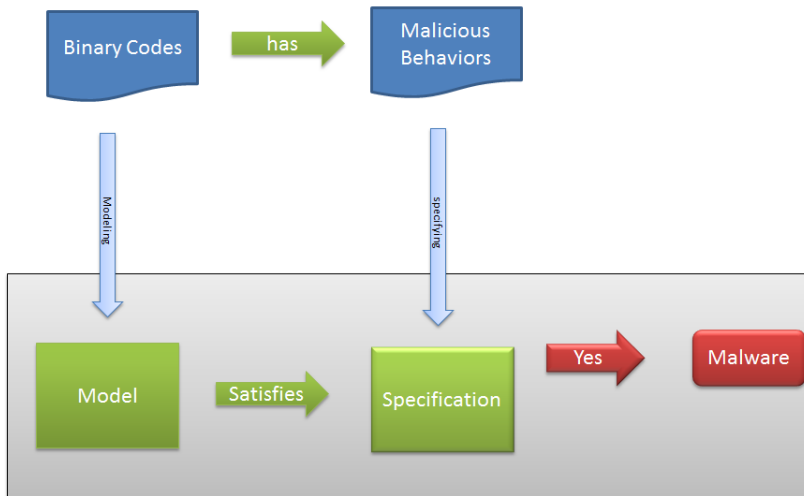
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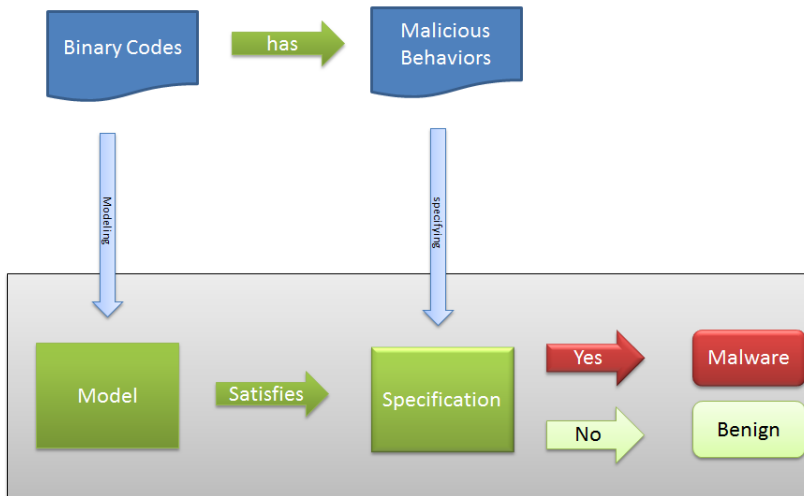
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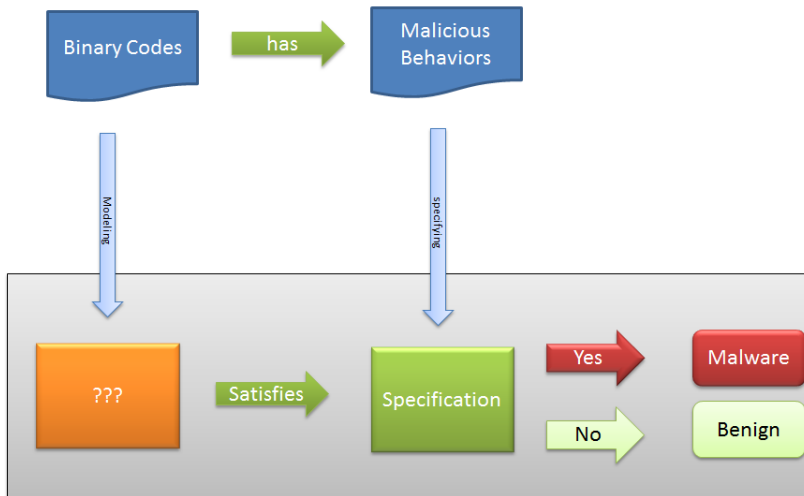
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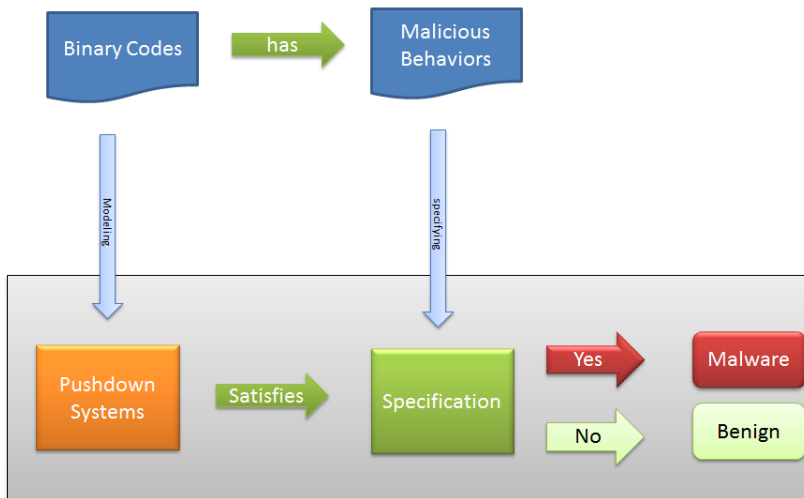
Model-checking for Malware Detection



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Model-checking for Malware Detection



Why Pushdown Systems?

Stack of binary codes

important for malware detection [Song and Touili 2012, 2013]

Pushdown Systems (PDSs)

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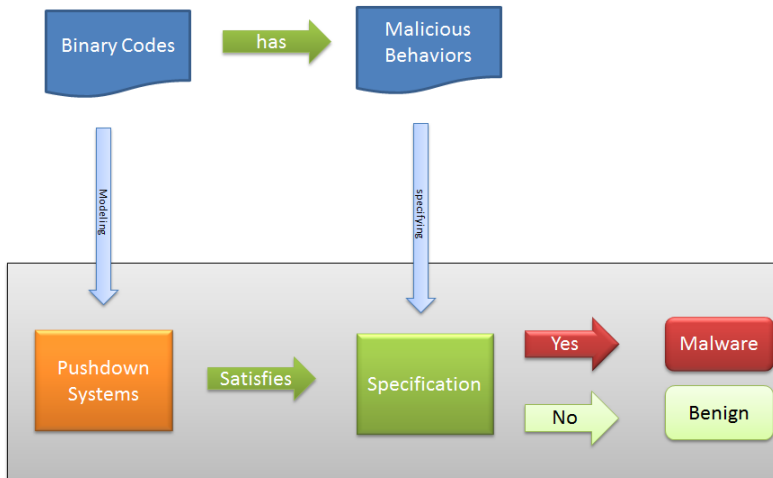
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PDSs for Binary Codes

- Control locations of PDSs correspond to program points
- Stack of PDSs correspond to stack of binary programs

Model-checking for Malware Detection



⇒ **Problem: This can be applied only for sequential programs. However, several malware is concurrent.**

The email worm Bagle

is a multithreaded malware:

- Main thread: register itself into the registry listing: to be started at the boot time
- Thread 2: listen on port 6777 to receive different commands; allow the attackers to upload new file, ...
- Thread 3: contacts a list of websites every 10 minutes: to announce the infection of the current machine
- Thread 4: is spawn to search on local drives to look for valid email addresses, ...then send itself to these found emails.

Concurrent Malware Example

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How instances of threads are spawn?

- Thread 1 dynamically spawn instances of Thread 2,3,4 depending on the needs
- The number of instances is not fixed, depending on specific executions
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⇒ **Bagle is a multithreaded malware, with dynamic thread creation during its execution. How to model such a concurrent malware?**

How to model such concurrent malware?

Ideas

- 1 PDS is a natural model for sequential malware.
- 2 \implies networks of PDSs can model concurrent malware.
- 3 \implies networks of PDSs with dynamic creation can model concurrent malware with dynamic creations.
- 4 \implies Dynamic Pushdown Networks [Bouajjani, Müller-Olm and Touili 2005] match our needs.

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Dynamic Pushdown Networks (DPNs)

- A DPN: a networks of Dynamic PDSs
- a Dynamic PDS: is a PDS with the ability to spawn new instances of PDSs during its runs

Definition of PDSs

A Pushdown System (PDS) \mathcal{P} is a tuple (P, Γ, Δ) , where

- P is a finite set of control locations
- Γ is a finite set of stack alphabet
- Δ is the set of transition rules of the following form:

- $(r_1): p\gamma \xrightarrow{\text{call}} p_1\gamma_1\gamma_2$

- $(r_2): p\gamma \xrightarrow{\text{ret}} p_1\epsilon$

- $(r_3): p\gamma \xrightarrow{\text{int}} p_1\omega$

where $p, p_1 \in P$, $\gamma, \gamma_1, \gamma_2 \in \Gamma$, $\omega \in \Gamma^*$

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A rule of the form $p\gamma \xrightarrow{\text{call}} p_1\gamma_1\gamma_2$ corresponds to a call statement

- usually models a statement of the form $\gamma \xrightarrow{\text{call } \text{proc}} \gamma_2$
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A configuration: $p\omega$ where $p \in P$ is the current control location, $\omega \in \Gamma^*$ is the current stack content.

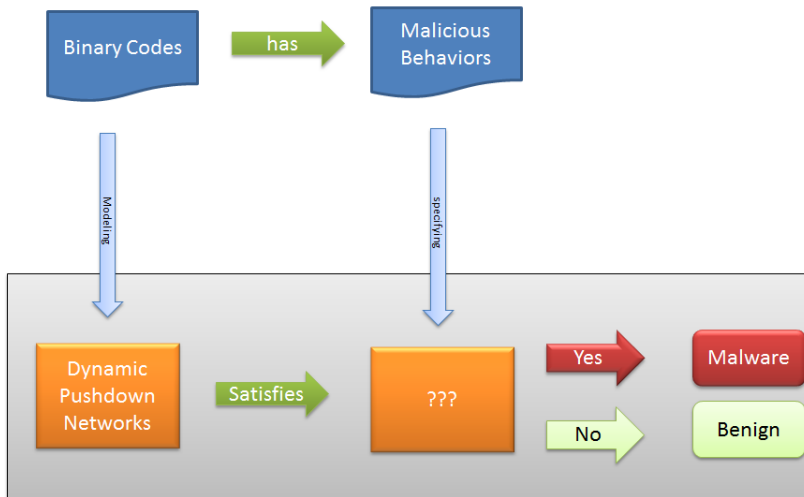
A Dynamic Pushdown Network (DPN) \mathcal{M} is a set $\{\mathcal{P}_1, \dots, \mathcal{P}_n\}$ s.t. for every $1 \leq i \leq n$, $\mathcal{P}_i = (P_i, \Gamma_i, \Delta_i)$ is a Dynamic Pushdown System (DPDS)

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- $(Spawn)(r_4) p\gamma \xrightarrow{call}_i p_1 \gamma_1 \gamma_2 \triangleright p_s \omega_s$
- $(Spawn)(r_5) p\gamma \xrightarrow{ret}_i p_1 \epsilon \triangleright p_s \omega_s$
- $(Spawn)(r_6) p\gamma \xrightarrow{int}_i p_1 \omega_1 \triangleright p_s \omega_s$

Model-checking for Malware Detection



Recent works: extensions of LTL, CTL were used as specifications

- CTPL [Kinder, Katzenbeisser, Schallhart and Veith 2005]
- SLTPL, SCTL [Song and Touili 2012, 2013]

However, these are not expressive enough for malicious behaviors

Malicious Behavior Example

Spyware Behavior

search directories for personal information (emails, bank account info, ...)

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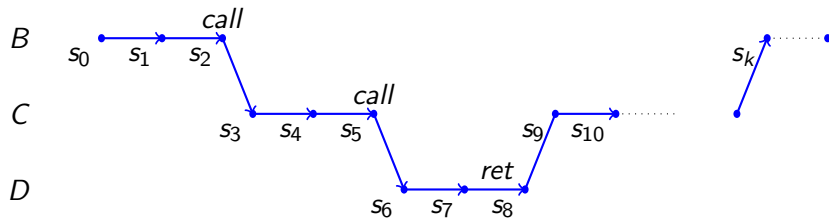
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Then,..

- Cannot be expressed by LTL or CTL since it requires that the return value of the function `FindFirstFileA` should be used as the input to the function `FindNextFileA`
- \implies we need a formalism that can talk about matching calls and returns \implies CARET.

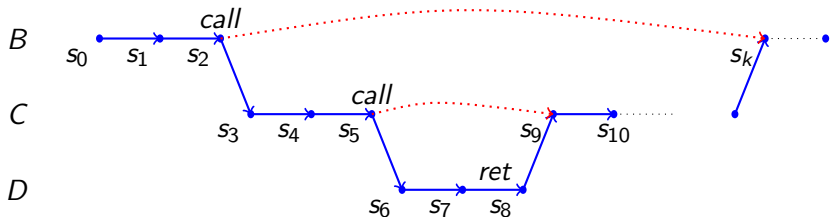
- linear temporal logic of Calls and Returns [Alur, Etesami and Madhusudan 2004]
- Interpreted over transition systems where each state is associated with a tag in the set {call, ret, int}
 - call : a call statement
 - ret : a return statement
 - int : an internal statement (neither call nor return)

- Global Successor(X^g): standard successor ($X^g(s_i) = s_{i+1}$)
- Global Path: standard path like for LTL



Abstract Successor

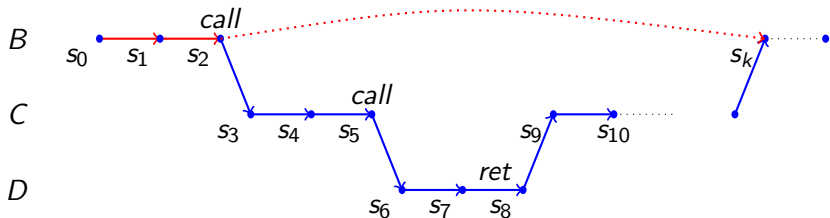
- Abstract Successor (X^a)
 - The abstract successor of a *call* is its corresponding return-point
- Abstract Path: apply repeatedly the abstract successor



Abstract Path

Abstract path:

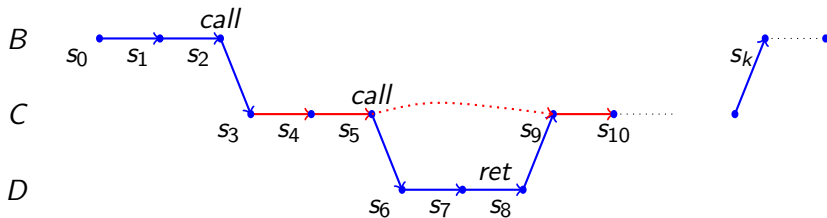
- From s_0 : $s_0 s_1 s_2 s_k \dots$



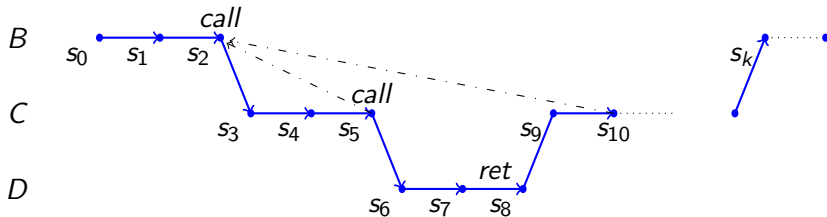
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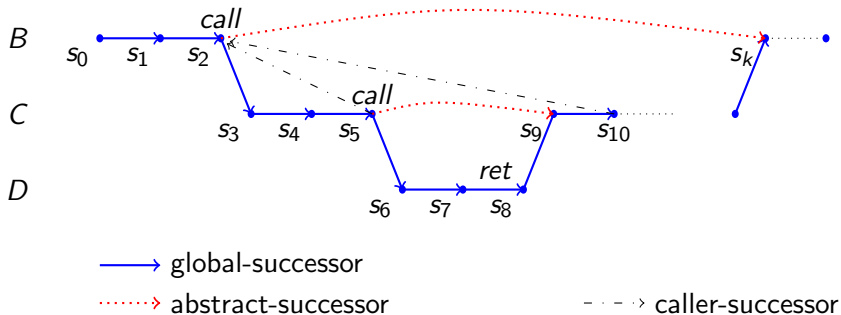
Abstract path:

- From s_3 : $s_3 s_4 s_5 s_9 s_{10} \dots$



- Caller Successors (X^c)
 - the caller successor of a point is the caller point of the current procedure
- Caller Path: apply repeatedly the caller successor





Given a finite set of atomic propositions AP . A CARET formula over AP is defined as follows:

$$\psi := e \mid \{call, ret, int\} \mid \psi \vee \psi \mid \neg\psi \mid X^g\psi \mid X^a\psi \mid X^c\psi \mid \psi U^a\psi \mid \psi U^g\psi \mid \psi U^c\psi$$

where

- $e \in AP$: atomic proposition
- X^g : global successor
- X^a : abstract successor
- X^c : caller successor
- U^g : until operator on global path
- U^a : until operator on abstract path
- U^c : until operator on caller path

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Using CARET to describe ...

$$\psi_{sf} = \bigvee_{d \in D} F^g(\text{call}(\text{FindFirstFileA}) \wedge X^a(\text{eax} = d) \wedge F^a(\text{call}(\text{FindNextFileA}) \wedge d\Gamma^*))$$

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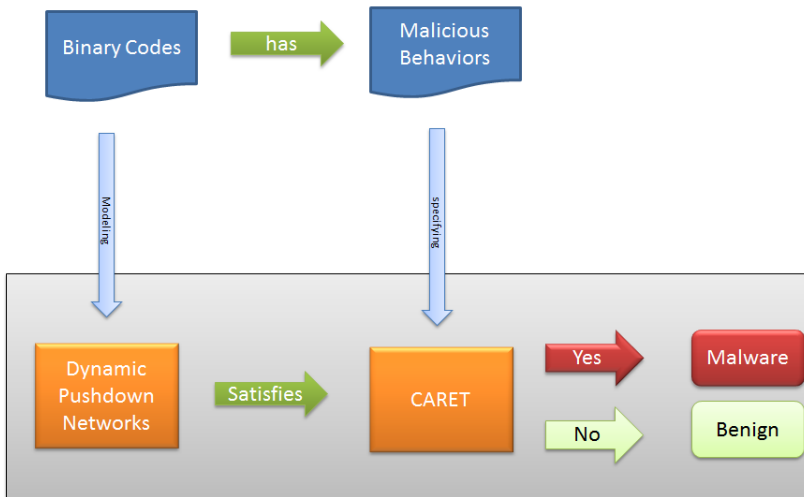
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⇒ ψ_{sf} : there exists a path s.t there is a call to *FindFirstFileA* where the return value is d , and after this call finishes, there is a call to *FindNextFileA* s.t d is used as parameter.

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Problem: $DPNs \models CARET??$

- ① model-checking LTL properties for networks of PDSs is **undecidable** [Kahlon and Gupta 2006], e.g., for properties that mix different indices of different threads like $F(a_i \wedge b_j)$

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- ④ \implies We consider: model-checking **single-indexed** CARET properties for DPNs, where:
 - **single-indexed** properties: properties in the form $f = f_1 \wedge f_2 \dots \wedge f_n$, where f_i is the CARET formula corresponding to \mathcal{P}_i

Given:

- a DPN $\mathcal{M} = \{\mathcal{P}_1, \mathcal{P}_2, \dots, \mathcal{P}_n\}$
- a single-indexed CARET formula $f = f_1 \wedge f_2 \dots \wedge f_n$

Model-checking problem:

- Does there exist an execution of \mathcal{M} s.t. every instance of the DPDS \mathcal{P}_i satisfies the corresponding CARET formula f_i ?

Theorem

Single-indexed CARET Model Checking for DPNs is decidable.

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- We compute BDPNs $\mathcal{BM} = \{\mathcal{BP}_1, \dots, \mathcal{BP}_n\}$ such that \mathcal{BP}_i is a kind of product between \mathcal{P}_i and the CARET formula f_i which ensures that:

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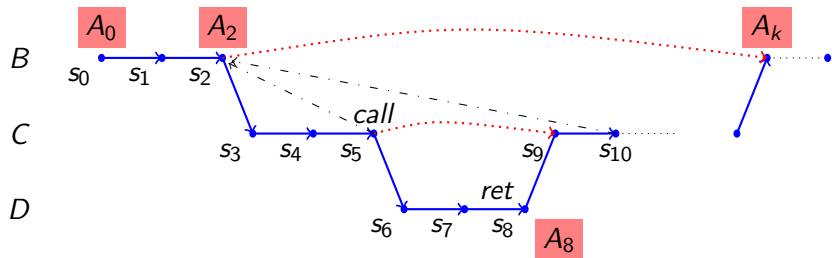
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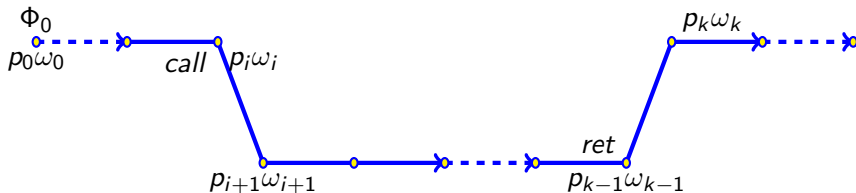
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 - The problem of checking whether an instance of \mathcal{P}_i starting from p_w satisfies f_i can be reduced to the membership problem of \mathcal{BP}_i

BDPDS Computation - Intuition

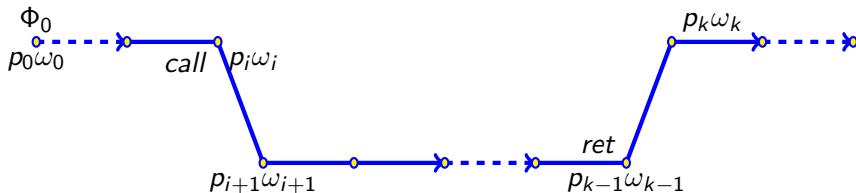
At state s_i , we encode a set of formulas A_i such that for every $\phi \in A_i$, ϕ holds at s_i



BDPDS Computation-X Operators-Call statements



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for $p_i\gamma \xrightarrow{\text{call}} p_{i+1}\gamma'\gamma''$ in \mathcal{P}_i :

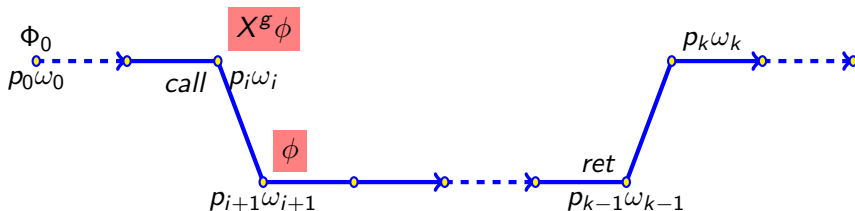
BDPDS Computation-X Operators-Call statements



for $p_i \gamma \xrightarrow{\text{call}} p_{i+1} \gamma' \gamma''$ in \mathcal{P}_i :

- $(\langle p_i, \{X^g \phi\} \rangle \gamma \rightarrow \langle p_{i+1}, \{\phi\} \rangle \gamma \gamma''$ in \mathcal{BP}_i

BDPDS Computation-X Operators-Call statements

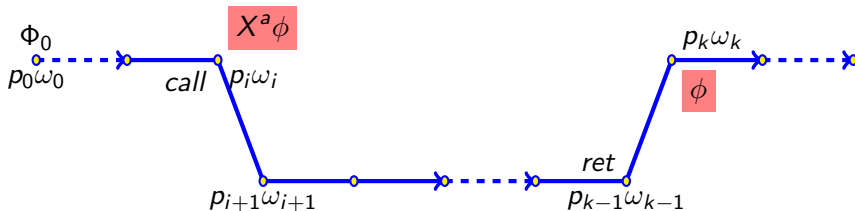


$$p_i \omega_i \models X^g \phi \text{ iff } p_{i+1} \omega_{i+1} \models \phi$$

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BDPDS Computation-X Operators-Call statements

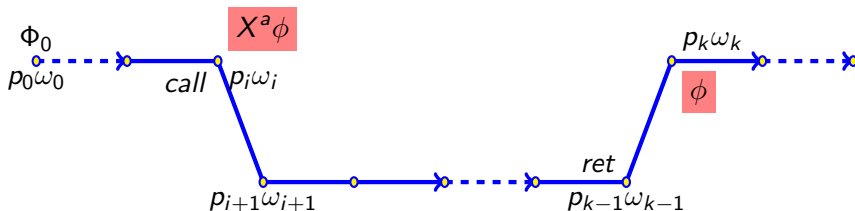


$$p_i\omega_i \models X^a\phi \text{ iff } p_k\omega_k \models \phi$$

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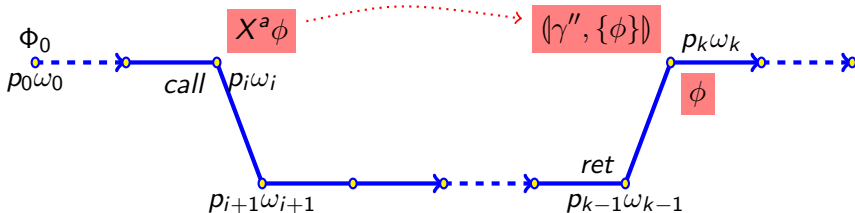


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BDPDS Computation-X Operators-Call statements

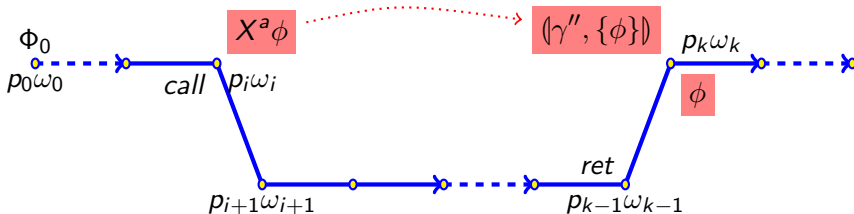


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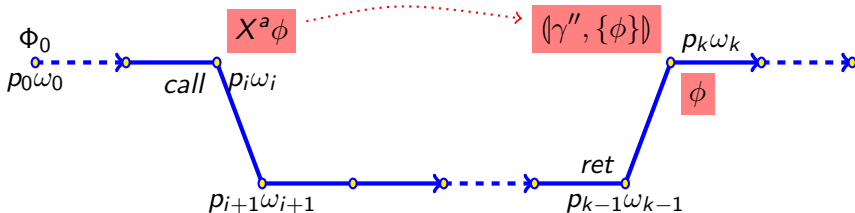
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BDPDS Computation-X Operators- Int statements



for $p_i \gamma \xrightarrow{int} p_{i+1} \omega$ in \mathcal{P}_i :

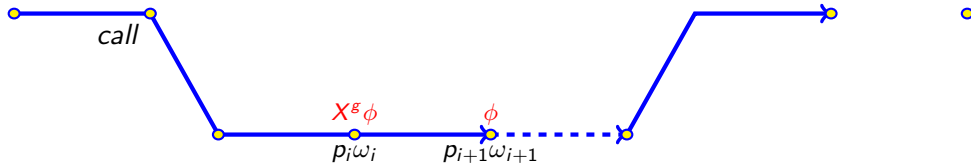
BDPDS Computation-X Operators- Int statements



for $p_i \gamma \xrightarrow{int} p_{i+1} \omega$ in \mathcal{P}_i :

- $(p_i, \{X^g \phi\}) \gamma \rightarrow (p_{i+1}, \{\phi\}) \omega$ in BP_i

BDPDS Computation-X Operators- Int statements



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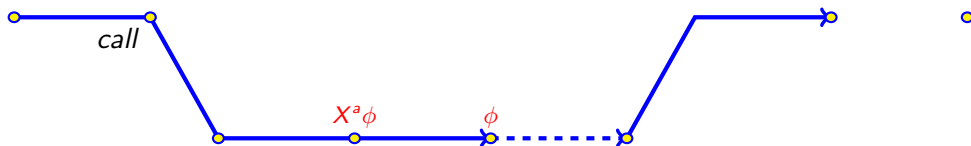
- $\langle p_i, \{X^g \phi\} \rangle \gamma \rightarrow \langle p_{i+1}, \{\phi\} \rangle \omega$ in \mathcal{BP}_i



for $p_i\gamma \xrightarrow{int} p_{i+1}\omega$ in \mathcal{P}_i :

- $(\langle p_i, \{X^g\phi\} \rangle \gamma) \rightarrow (\langle p_{i+1}, \{\phi\} \rangle \omega)$ in \mathcal{BP}_i
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for $p_i\gamma \xrightarrow{int} p_{i+1}\omega \triangleright p_s\omega_s$ in \mathcal{P}_i
($p_s\omega_s \in \mathcal{P}_j$):

BDPDS Computation-X Operators- Int statements



for $p_i\gamma \xrightarrow{int} p_{i+1}\omega$ in \mathcal{P}_i :

- $(\langle p_i, \{X^g\phi\} \rangle)\gamma \rightarrow (\langle p_{i+1}, \{\phi\} \rangle)\omega$ in \mathcal{BP}_i
- $(\langle p_i, \{X^a\phi\} \rangle)\gamma \rightarrow (\langle p_{i+1}, \{\phi\} \rangle)\omega$ in \mathcal{BP}_i

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($p_s\omega_s \in \mathcal{P}_j$):

- $(\langle p_i, \{X^g\phi\} \rangle)\gamma \rightarrow (\langle p_{i+1}, \{\phi\} \rangle)\omega \triangleright (\langle p_s, f_j \rangle)\omega_s$ in \mathcal{BP}_i
- $(\langle p_i, \{X^a\phi\} \rangle)\gamma \rightarrow (\langle p_{i+1}, \{\phi\} \rangle)\omega \triangleright (\langle p_s, f_j \rangle)\omega_s$ in \mathcal{BP}_i

Theorem

Given a DPN $\mathcal{M} = \{\mathcal{P}_1, \dots, \mathcal{P}_n\}$, a single-indexed CARET formula $f = f_1 \wedge f_2 \dots \wedge f_n$, we can compute a BDPN $\mathcal{BM} = \{\mathcal{BP}_1, \dots, \mathcal{BP}_n\}$ such that $\mathcal{M} \models f$ iff \mathcal{BM} has an accepting run.

DPNs communicating via Locks (L-DPNs)

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Theorem

Single-indexed CARET model-checking for L-DPNs with nested Lock access can be reduced to single-indexed CARET model-checking for DPNs

Thank you for your listening!