

Regular path clauses and their application in solving loops

Bishoksan Kafle¹ **John P. Gallagher**^{1,2} Manuel Hermenegildo^{1,3}
Maximiliano Klemen¹ Pedro López-García¹ José F. Morales^{1,3}

¹IMDEA Software Institute, ²Roskilde University, and ³T.U. Madrid (UPM)

HCVS'21, Virtual

Standard approach for solving loops:

- extract recurrences from the loop, and
- solve them to get a closed-form expression (possibly) using a (combination of) Computer Algebra Systems (CASs).

Resource analysis: [Wegbreit Comm. of the ACM'74, Debray et al. PLDI'90 and TOPLAS'93, Navas et al. ICLP'07, Albert et al. TOCL'13].

Invariant synthesis: [Farzan et al. FMCAD'15, Kincaid et al. POPL'18-POPL'19, Humenberger et al. VMCAI'18].

Computer Algebra Systems (CASs)

Pros:

- Can derive **non-linear functions** including polynomial, exponential, logarithmic, ...
- Can produce very **precise solutions** for some classes of recurrences.

Cons:

- Can only solve a subset of all possible recurrences.
- Typically:
 - Recurrences with a **single recursive case**.
 - Recurrences involving **univariate functions**.

Recurrences derived from programs may not be *solvable* by CASs:

- Usually have multiple paths (if ... then ... else inside a loop) → multiple recursive cases.
- Manipulate multiple variables → multivariate recurrences.

Goal

Use CASs to solve **program loops** (infer loop invariants) by:

- Systematically **transforming programs**, expressed as constrained Horn clauses (CHCs), to obtain recurrences that are **solvable by CASs**

Example: a program and its CHC representation

```
int a, b; //input
while (a > 0) {
  if (b > 0) then
    b --;
  else b = b + a;
    a --; }
```

```
c1: wh(a, b)  $\leftarrow$  a > 0, b > 0, wh(a, b - 1).
c2: wh(a, b)  $\leftarrow$  a > 0, b  $\leq$  0, wh(a - 1, b + a).
c3: wh(a, b)  $\leftarrow$  a  $\leq$  0.
```

(a) Ex. program.

(b) CHCs (c_i is a clause identifier).

- It exhibit a multi-path loop (with paths c_1 and c_2).
- It manipulates two variables, a, b .

→ CASs cannot be directly applied.

1 Multi-path loops \longrightarrow single-path loops

2 Multi-argument functions \longrightarrow single-argument functions

Removing multi-path loops: Procedure

Multi-path loops \longrightarrow single-path loops

Input: a CHC program P and its CFG (w/ entry and exit nodes).

Output: an “equivalent” CHC program P' without multi-path loops.

Process sketch:

- 1 Compute a regexp e describing all paths from entry to exit (using Tarjan's alg.)
- 2 Transform e into an equivalent regexp e' without $+$ op. within a $*$.
- 3 Construct path clauses P' using P and e' ; return P' .

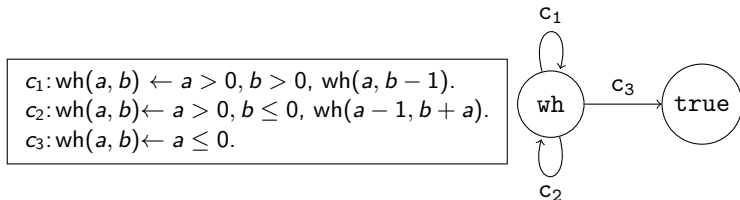
Related work:

- **Merge paths:** [Albert et al. TOCL'13, Farzan et al. FMCAD'15, Kincaid et al. POPL'18-POPL'19].
- **Deal with each path separately and combine their polynomial ideals:** [Humenberger et al. VMCAI'18].
- **Control-flow refinement:** [Sharma et al. CAV'11, Puebla et al. JLP'99, Doménech et al. TPLP'19].

Representing loops as regular expressions

- Program paths can be described by regular expressions, eg.:

$(c_1 + c_2)^* c_3$ describes all paths through the following loop



- Regular expressions can be transformed into other equivalent expressions, e.g.:

$$(c_1 + c_2)^* c_3 \equiv c_1^* (c_2 c_1^*)^* c_3 \equiv c_2^* (c_1 c_2^*)^* c_3.$$

Construction of path clauses corresponding to $*$ expression

Given $c_1: wh(a, b) \leftarrow \underbrace{a > 0, b > 0, a' = a, b' = b - 1}_{\phi}, wh(a', b')$, the path clauses given by c_1^* starting from node wh are:

$$\begin{aligned} path_{c_1^*}(wh(a, b), wh(a, b)) &\leftarrow \text{true.} && (\text{note: } e^* = e^*e) \\ path_{c_1^*}(wh(a, b), wh(a'', b'')) &\leftarrow path_{c_1^*}(wh(a, b), wh(a', b')), \\ &\quad path_{c_1}(wh(a', b'), wh(a'', b'')). \end{aligned}$$

OR

$$\begin{aligned} path_{c_1^*}(wh(a, b), wh(a, b)) &\leftarrow \text{true.} && (\text{note: } e^* = ee^*) \\ path_{c_1^*}(wh(a, b), wh(a'', b'')) &\leftarrow path_{c_1}(wh(a, b), wh(a', b')), \\ &\quad path_{c_1^*}(wh(a', b'), wh(a'', b'')). \end{aligned}$$

where $path_{c_1}(wh(a, b), wh(a', b')) = \phi$

Simplification and renaming of path clauses

Given

$$\begin{aligned} path_{c_1^*}(wh(a, b), wh(a, b)) &\leftarrow \text{true}. \\ path_{c_1^*}(wh(a, b), wh(a'', b'')) &\leftarrow path_{c_1^*}(wh(a, b), wh(a', b')), \\ &\quad path_{c_1}(wh(a', b'), wh(a'', b'')). \\ path_{c_1}(wh(a', b'), wh(a'', b'')) &\leftarrow a' > 0, b' > 0, a'' = a', b'' = b' - 1. \end{aligned}$$

Renaming and simplifying we obtain:

$$\begin{aligned} wh_2(a, b, a, b) &\leftarrow \text{true}. \\ wh_2(a, b, a', b' - 1) &\leftarrow wh_2(a, b, a', b'), \quad a' > 0, \quad b' > 0. \end{aligned}$$

Construction of path clauses corresponding to an expr. e

c	$path_c(p(\mathbf{x}), q(\mathbf{x}')) \leftarrow \phi.$, where clause $p(\mathbf{x}) \leftarrow \phi, q(\mathbf{x}') \in P$ has identifier c
ϵ	$path_\epsilon(p(\mathbf{x}), p(\mathbf{x})) \leftarrow \text{true}.$
\emptyset	no clause
$e_1 e_2$	$path_{e_1 e_2}(p(\mathbf{x}), z) \leftarrow path_{e_1}(p(\mathbf{x}), q(\mathbf{x}')), path_{e_2}(q(\mathbf{x}'), z).$, for each $q \in \text{firstpred}(e_2)$
$e_1 + e_2$	$path_{e_1 + e_2}(p(\mathbf{x}), z) \leftarrow path_{e_1}(p(\mathbf{x}), z).$ $path_{e_1 + e_2}(p(\mathbf{x}), z) \leftarrow path_{e_2}(p(\mathbf{x}), z).$
e^*	$path_{e^*}(p(\mathbf{x}), p(\mathbf{x})) \leftarrow \text{true}.$ $path_{e^*}(p(\mathbf{x}), p(\mathbf{x}'')) \leftarrow path_{e^*}(p(\mathbf{x}), p(\mathbf{x}')), path_e(p(\mathbf{x}'), p(\mathbf{x}'')).$

Path clauses for the example program

$c_1: \text{wh}(a, b) \leftarrow a > 0, b > 0, \text{wh}(a, b - 1).$
 $c_2: \text{wh}(a, b) \leftarrow a > 0, b \leq 0, \text{wh}(a - 1, b + a).$
 $c_3: \text{wh}(a, b) \leftarrow a \leq 0.$

Path clauses based on $(c_1^*(c_2c_1^*)^*)c_3$

$\text{path}(\text{wh}(a, b), \text{true}) \leftarrow \text{wh}_2(a, b, a', b'), \text{wh}_5(a', b', a'', b''), a'' \leq 0.$

$\text{wh}_2(a, b, a, b) \leftarrow \text{true}.$

$\text{wh}_2(a, b, a', b' - 1) \leftarrow \text{wh}_2(a, b, a', b'), a' > 0, b' > 0.$

$\text{wh}_5(a, b, a, b) \leftarrow \text{true}.$

$\text{wh}_5(a, b, a'', b'') \leftarrow \text{wh}_5(a, b, a', b'), a' > 0, b' \leq 0, \text{wh}_2(a' - 1, b' + a', a'', b'').$

Result: multi-paths \longrightarrow nested single-paths

- 1 Multi-path loops \longrightarrow single-path loops
- 2 Multi-argument functions \longrightarrow single-argument functions

① **Instrument** path clause with a counter k .

- Given $\text{path}_{e^*}(\mathbf{x}, \mathbf{x}_2) \leftarrow \phi(\mathbf{x}_1, \mathbf{x}_2), \text{path}_{e^*}(\mathbf{x}, \mathbf{x}_1)$.
- Path clauses with a counter k are:

$$\begin{aligned}\text{path}_{e^*}(k, \mathbf{x}, \mathbf{x}_2) &\leftarrow k > 0, \phi(\mathbf{x}_1, \mathbf{x}_2), \text{path}_{e^*}(k - 1, \mathbf{x}, \mathbf{x}_1). \\ \text{path}_{e^*}(k, \mathbf{x}, \mathbf{x}) &\leftarrow k = 0.\end{aligned}$$

- ② Then, given an input tuple \mathbf{x} and k , **set up equations** for **output tuple \mathbf{x}_2** using the path clause, using methods such as in (Debray et al., TOPLAS'93).
- ③ Detect and remove **symbolic constants** from the equations; obtaining single-argument functions.
- ④ **Solve** the resulting equations using CASs and **replace k** in the solution with the value of the **ranking function** in the initial state of the original loop clause.

Multi-args \rightarrow single-arg: [Farzan et al. FMCAD'15, Albert et al. TOCL'13]

Example

Given $\text{wh}(x_1, y_1) \leftarrow x_1 > 0, y_1 > 0, x_2 = x_1 - 1, y_2 = y_1 + x_1, \text{wh}(x_2, y_2)$,
the path clauses with a counter k are:

$$\begin{aligned}\text{path}(k, x, y, x_2, y_2) &\leftarrow k > 0, k_1 = k - 1, x_2 = x_1 - 1, y_2 = y_1 + x_1, \\ &\quad \text{path}(k_1, x, y, x_1, y_1), \\ &\quad x_1 > 0, y_1 > 0. \\ \text{path}(k, x, y, x, y) &\leftarrow k = 0.\end{aligned}$$

The outputs x_2, y_2 represent the values of x, y after k iterations of the loop and is completely determined by the inputs k, x, y .

Extracted Recurrences

Hence, given

$$\text{path}(k, x, y, x_2, y_2) \leftarrow \begin{array}{l} k > 0, k_1 = k - 1, x_2 = x_1 - 1, y_2 = y_1 + x_1, \\ \text{path}(k_1, x, y, x_1, y_1), x_1 > 0, y_1 > 0. \end{array}$$

we obtain the following recurrences

$$\text{wh}^x(k, x, y) = \begin{cases} \text{wh}^x(k - 1, x, y) - 1, & \text{for } k > 0, \\ x, & \text{for } k = 0 \end{cases}$$

$$\text{wh}^y(k, x, y) = \begin{cases} \text{wh}^y(k - 1, x, y) + \text{wh}^x(k - 1, x, y), & \text{for } k > 0, \\ y, & \text{for } k = 0 \end{cases}$$

where $\text{wh}^v(k, x, y)$ defines the values of v after k iterations of the `wh` loop.

Since the recurrences involve multi-argument functions, they cannot be solved by the CASs.

Multi-args functions to single-arg functions

Using data-flow analysis ([reaching definitions analysis](#)), we can detect that x, y are [symbolic constants](#) in the following equation.

$$\text{wh}^x(k, x, y) = \begin{cases} \text{wh}^x(k - 1, x, y) - 1, & \text{for } k > 0, \\ x, & \text{for } k = 0 \end{cases}$$

since they cannot [affect](#) the solution of the equations

- [remove](#) them as arguments, and
- [replace](#) their occurrence elsewhere by a constant function returning their values.

Solving recurrences for $\text{wh}^x(k, x, y)$

$$\text{wh}^x(k) = \begin{cases} \text{wh}^x(k-1) - 1, & \text{for } k > 0, \\ c_x, & \text{for } k = 0 \end{cases}$$

- Can be solved using existing CASs, obtaining $\text{wh}^x(k) = c_x - k$ as a **closed-form** solution.
- This is also the solution of the original equation, thus we have $\text{wh}^x(k, x, y) = x - k$.

Solving recurrences for $\text{wh}^y(k, x, y)$

$$\text{wh}^y(k, x, y) = \begin{cases} \text{wh}^y(k-1, x, y) + \text{wh}^x(k-1, x, y), & \text{for } k > 0, \\ y, & \text{for } k = 0 \end{cases}$$

Reusing the solution of $\text{wh}^x(k, x, y)$, we obtain

$$\text{wh}^y(k, x, y) = \begin{cases} \text{wh}^y(k-1, x, y) + x - k + 1, & \text{for } k > 0, \\ y, & \text{for } k = 0 \end{cases}$$

Since x, y are **symbolic constants**, we get

$$\text{wh}^y(k) = \begin{cases} \text{wh}^y(k-1) + c_x - k + 1, & \text{for } k > 0, \\ c_y, & \text{for } k = 0 \end{cases}$$

- which can be solved to yield $\text{wh}^y(k) = c_y - 1/2k(k - 2x - 1)$ and hence $\text{wh}^y(k, x, y) = y - 1/2k^2 + kx + 1/2k$.

Obtaining bounds on k

What is the value of the counter variable k ?

- Assuming the wh loop has a ranking function, $k \in [0, r]$ where r is the value of ranking function in the initial state.
- assume $wh(x_1, y_1)$ is the call at the start of the loop. Then the loop executes $k \in [0, x_1]$ times.
- Thus the final value of x_1 and x_2 resp. are $[0, x_1]$ and $[y_1 - 1/2x_1^2, y_1 + 1/2x_1 + x_1^2]$; obtained using interval arithmetic.

Putting it all together

We achieved

- Multi-path loops \longrightarrow Single-path loops (through transformation of regular expressions).
- Multi-argument functions \longrightarrow single-argument functions (through counter instrumentation and detection and removal of symbolic constants).

Pros:

- Besides overcoming these limitations of CASs, also ensures that the resulting recurrences.
 - Contain **no mutual recursion**.
 - Contain **only a decreasing argument**(k).

Cons:

- **Shifts** the problem to **finding bounds on k** .
- **Success** of our method depends on external tools such as **ranking function synthesizers and CASs**.
- The use of **interval arithmetic** to infer bounds on variable values can result in **imprecision**.
- Transforming a given **program** into a **multi-path loop** could cause an **exponential blow-up in size**.

Future:

- Investigate the **choice of regular expressions**.
- Extend our approach to **extract and solve recurrence inequations**.
- Extend it to **handle non-linear loops**.

The end!

Thanks for your attention!