

# A formalization of metric spaces in HOL Light

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# Background

## Geometry:

- ▶ **Metric spaces** are an indispensable tool in mathematics (geometry, analysis, algebra, ...).

## Computer Science:

- ▶ Computer can be useful for **theorem proving**:
  - ▶ **Discover** new theorems (*automated theorem proving*);
  - ▶ **Check** proofs (*computer checked mathematics*).

## This work:

- ▶ **Implement** metric spaces in the **HOL Light** theorem prover.

# The tool

## HOL Light theorem prover

- ▶ **Interactive** theorem prover.
- ▶ **Simple foundation** (typed lambda calculus, 10 rules, 3 axioms).
- ▶ Easy to **program and extend** (write your own *tactics*).
- ▶ Remarkable **standard library** (real and complex analysis, linear algebra, topology and geometry, ...).

# This work

## Our main results:

- ▶ A **definition of metric spaces** (overcome technical issues related to the logical foundation).
- ▶ Computer **verification of some classical results** about (complete) metric spaces.
- ▶ Applications to Ordinary Differential Equations.
- ▶ (*Main topic of this talk*) Implementation of a **decision procedure** for the *elementary theory of metric spaces*.

# Comparison with other work (in HOL)

- ▶ Euclidean Spaces in HOL Light [Harrison 2005]
  - ▶ decision procedure (NORM\_ARITH)
  - ▶ only euclidean metric
- ▶ Metric spaces in Isabelle/HOL [Immler and Hölzl 2012]
  - ▶ Isar proof language (more readable)
  - ▶ *Total* metric spaces
    - ▶ axiomatic classes
    - ▶ adequate for most applications
    - ▶ some limitations in expressivity spaces (e.g.,  $L^p$  spaces)
  - ▶ no specialized decision procedure
- ▶ Metric spaces in HOL Light (this work)
  - ▶ *Partial* Metric spaces
    - ▶ can reason subspaces and families of metric spaces
  - ▶ Decision procedure METRIC\_ARITH

# Elementary theory of Metric spaces

## Structure

Carrier:  $M$  the domain (the set of points)

Distance:  $d: M \times M \longrightarrow \mathbb{R}$

## Axioms

Non-negativity:  $d(x, y) \geq 0$

Indiscernibility:  $d(x, y) = 0$  if and only if  $x = y$

Symmetry:  $d(x, y) = d(y, x)$

Triangle inequality:  $d(x, z) \leq d(x, y) + d(y, z)$

## Esempi di spazi metrici

- ▶ Standard metric of  $\mathbb{R}^n$ :

$$d(x, y) = \sqrt{(x_1 - y_1)^2 + \cdots + (x_n - y_n)^2}$$

- ▶  $L^\infty$  metric on  $\mathbb{R}^n$ :

$$d_\infty(x, y) = \max \{|x_1 - y_1|, \dots, |x_n - y_n|\}$$

- ▶ *Manhattan* metric ( $L_1$  metric) on  $\mathbb{R}^n$ :

$$d_1(x, y) = |x_1 - y_1| + \cdots + |x_n - y_n|$$

- ▶ Metric of a normed vector space:

$$d(u, v) = \|u - v\|$$

- ▶  $L^\infty$  metric on the space of continuous functions on  $[0, 1]$

$$d_\infty(f, g) = \max \{|f(x) - g(x)| : 0 \leq x \leq 1\}$$

# Complete metric spaces

**Cauchy sequences:** The distance between its terms becomes arbitrary small after a certain index.

**Easy result:** Every convergent sequence is a Cauchy sequence.

**Definition:** A metric space is *complete* if the converse it is also true.

## Some results proved:

- ▶ Baire category theorem.
- ▶ Banach fixed-point theorem.
- ▶ Proof of completeness of some notable spaces ( $\mathbb{R}^n$ , bounded functions, continuous bounded functions).

# Example: the Banach Fixed Point Theorem

## Theorem (Banach)

*Every contraction  $f : M \rightarrow M$  on a non empty complete metric space  $M$  has an unique fixed-point.*

Formal statement in HOL Light:

$$\begin{aligned} &\vdash \forall m \ f \ k. \\ &\quad \neg(\text{mspace } m = \emptyset) \wedge \text{mcomplete } m \wedge \\ &\quad (\forall x. x \in \text{mspace } m \implies f \ x \in \text{mspace } m) \wedge \\ &\quad k < 1 \wedge \\ &\quad (\forall x \ y. x \in \text{mspace } m \wedge y \in \text{mspace } m \\ &\quad \implies \text{mdist } m \ (f \ x, f \ y) \leq k * \text{mdist } m \ (x, y)) \\ &\implies (\exists! x. x \in \text{mspace } m \wedge f \ x = x) \end{aligned}$$

# Example: the Banach Fixed Point Theorem

## Theorem (Banach)

*Every contraction  $f : M \rightarrow M$  on a non empty complete metric space  $M$  has an unique fixed-point.*

Formal statement in HOL Light:

$$\begin{aligned} &\vdash \forall M f k. \\ &\quad \neg(M = \emptyset) \wedge \text{complete } M \wedge \\ &\quad (\forall x. x \in M \implies f(x) \in M) \wedge \\ &\quad k < 1 \wedge \\ &\quad (\forall x y. x \in M \wedge y \in M \\ &\quad \quad \implies d(f(x), f(y)) \leq k d(x, y)) \\ &\quad \implies (\exists! x. x \in M \wedge f(x) = x) \end{aligned}$$

## Example: Continuous bounded functions

One key example is the space of continuous bounded functions with  $L^\infty$ -metric.

For  $f, g: X \rightarrow M$  bounded functions define

$$d_\infty(f, g) = \sup_{x \in X} d_M(f(x), g(x)).$$

If  $M$  is complete, the function space is complete:

$\vdash \forall \text{top } m. \text{ mcomplete } m \implies \text{ mcomplete } (\text{cfunspace top } m)$

We will use this fact in the proof of the Picard-Lindelöf theorem.

## A decision procedure for metric space

We implemented a **decision procedure** METRIC\_ARITH for general metric spaces (similar to Harrison's NORM\_ARITH).

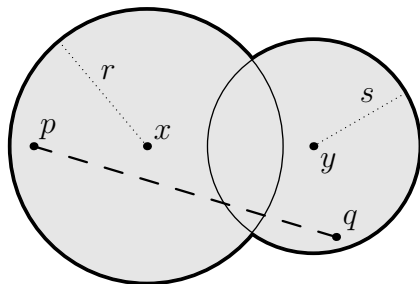
Based on a work of Solovay, Arthan and Harrison [2012].

Can automatically prove basic facts like **“triangle law”** lemmas.

Can handle a wider range of quantifiers (basically a  $\forall\exists$  fragment of the theory).

## A decision procedure for metric space (Example)

Given  $B_1, B_2$  two intersecting open balls of radius  $r, s$  respectively, the diameter of their union  $B_1 \cup B_2$  is less than  $2(r + s)$ .



$$\begin{aligned} \forall M \ x \ y \ r \ s. \quad & \neg(\text{DISJOINT } (B(x,r)) \ (B(y,s))) \\ & \implies \forall p \ q. \ p \in B(x,r) \cup B(y,s) \wedge \\ & \quad q \in B(x,r) \cup B(y,s) \\ & \implies d(p,q) < 2 \ (r + s) \end{aligned}$$

# Undecidability of the theory of metric spaces

## The elementary theory of metric spaces is undecidable

- ▶ Early result due to Bondi [1973].
- ▶ A simple proof [Kutz 2003] can be obtained by considering metric spaces associated to graph and reducing the problem to the undecidability about problems on binary relations

## Problem

Find a decidable class of valid formulas in the language of the metric spaces.

# Decidable fragments $\forall\exists$ and $\exists\forall$

## Definition

- ▶ A formula  $\phi$  is  $\forall\exists$  if
  - ▶ is in prenex form
  - ▶ no universal quantifier occurs in the scope of an existential one.
- ▶ In short:

$$\phi \equiv \forall \bar{x}. \exists \bar{y}. \psi$$

- ▶  $\exists\forall$  formulas are defined similarly:

$$\phi \equiv \exists \bar{x}. \forall \bar{y}. \psi$$

## Theorem (Bernays-Schönfinkel)

- (1) The class of valid  $\forall\exists$  sentences without function symbols is decidable.
- (2) The class of satisfiable  $\exists\forall$  sentences without function symbols is decidable.

This results can extended to important cases where function symbols occur.

## Theorem (Tarski)

The theory of real closed fields is decidable.

Putting the two results together we can obtain a decidability result for metric spaces.

# $\forall\exists_p$ and $\exists\forall_p$ sentences

## Definition

- ▶ A sentence in the language of metric spaces  $\phi$  is  $\forall\exists_p$  if
  1. is in prenex form;
  2. no universal quantifier over points is in the scope of an existential quantifier (of any sort);
- ▶  $\exists\forall_p$  sentences are defined analogously.

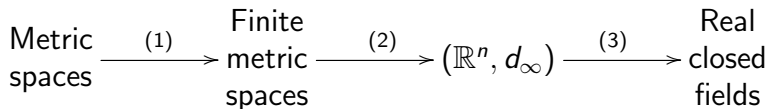
## Remark

Since universal quantifiers commute up to logical equivalence, any  $\forall\exists_p$  sentence  $\phi$  can be assumed to be of the form

$$\phi \equiv \forall x_1, \dots, x_n. \exists \bar{y} / Q \bar{z}. \psi$$

# Idea

The validity of an  $\forall\exists_p$  formula in the language of metric spaces can be reduced to the validity of a formula of real closed fields through the following three steps:



## Theorem (Step 1: Reduction to finite metric spaces)

Given an  $\forall\exists\rho$  sentence in the language of metric spaces

$\phi \equiv \forall x_1, \dots, x_n. \exists \bar{y}/Q\bar{z}. \psi$  TFAE:

- (1)  $\phi$  is valid in all (non empty) metric spaces;
- (2)  $\phi$  is valid in all finite metric spaces with no more than  $\max\{n, 1\}$  points.

Proof (1)  $\implies$  (2).

Trivial. □

Proof (2)  $\implies$  (1).

Let  $\phi$  be valid in all (non empty) finite metric spaces with at most  $n$  points.

Given  $n$  points  $x_1, \dots, x_n$ , the formula  $\rho \equiv \exists \bar{y}/Q\bar{z}. \psi$  is valid on the metric space  $S := \{x_1, \dots, x_n\} \subseteq M$ .

Then  $\phi$  is valid on  $M$ . □

Construction (Step 2: from finite metric spaces to  $\mathbb{R}_\infty^n$ )

Let  $(M, d)$  be a finite metric space with  $n$  points  $p_1, \dots, p_n$ .

Consider  $\mathbb{R}_\infty^n = (\mathbb{R}^n, d_\infty)$ , where

$$d_\infty(x, y) = \max\{|x_1 - y_1|, \dots, |x_n - y_n|\}$$

Then the application

$$f_M: M \rightarrow \mathbb{R}^n$$

given by

$$f_M(p) = (d(p, p_1), \dots, d(p, p_n))$$

is an isometric embedding.

## Theorem

The class of logically valid  $\forall\exists_p$  sentences in the language of metric space is decidable.

**Proof:** Taking the negation we look for a decision procedure for the satisfiability of  $\exists\forall_p$  sentences.

Let  $\phi \equiv \exists x_1, \dots, x_n. \forall \bar{y}/Q\bar{z}. \psi$ .

Thanks to previous theorem,  $\phi$  is satisfiable iff exists an interpretation of  $x_1, \dots, x_n$  in a metric space  $M$  with at most  $\max(n, 1)$  points satisfying  $\forall \bar{y}/Q\bar{z}. \psi$ .

By replacing every subformula of  $\phi$  of the form  $\forall y. \psi$  with the conjunction  $\psi[x_1/y] \wedge \dots \wedge \psi[x_n/y]$  we obtain a sentence which is equisatisfiable with  $\phi$  without universal quantifiers over points.

Therefore, we can assume that  $\phi$  has the form  $\exists x_1 \dots x_n. \psi$  where only quantifiers over scalars occurs in  $\phi$ .

**To be continued ...**

## Proof (second part)

By using  $f : M \rightarrow \mathbb{R}_\infty^n$ , we have that  $\phi$  is satisfiable iff it is so on  $\mathbb{R}_\infty^n = (\mathbb{R}^n, d_\infty)$ .

Let  $x_{ij}$ ,  $1 \leq i, j \leq n$  be new scalar variables ( $f_M(x_i) = (x_{i1}, \dots, x_{in})$ ) and  $\psi'$  the formula obtained by replacing in  $\psi$

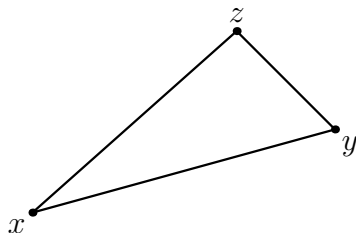
- ▶ every subterm of the form  $x_s = x_t$  with  $x_{s1} = x_{t1} \wedge \dots \wedge x_{sn} = x_{tn}$  and
- ▶ every subterm of the form  $d(x_s, x_t)$  with  $d_\infty(f_M(x_s), f_M(x_t)) = \max\{|x_{s1} - x_{t1}|, \dots, |x_{sn} - x_{tn}|\}$

$\exists x_1 \dots x_n. \psi$  is satisfiable iff  $\phi' := \exists x_{11}, x_{12} \dots x_{nn}. \psi'$  is satisfiable.

Now,  $\phi'$  is a formula without variables on points, then we can apply a decision procedure for real closed fields.

**QED**

## Example: Reverse triangle inequality



**Triangle inequality:**

$$d(x, y) \leq d(x, z) + d(z, y)$$

**Reverse triangle inequality:**

$$|d(x, z) - d(z, y)| \leq d(x, y)$$

## Reverse triangle inequality

**“Human” proof** of the reverse triangle inequality

$$|d(x, y) - d(y, z)| \leq d(x, z)$$

1. Use  $|a - b| \leq c \iff a \leq c + b \wedge b \leq c + a$ . We get

$$d(x, y) \leq d(x, z) + d(y, z)$$

$$d(y, z) \leq d(x, z) + d(x, y)$$

2. both inequalities are instances of the triangle inequality. QED

# Reverse triangle inequality

**Machine proof** of the reverse triangle inequality

$$|d(x, y) - d(y, z)| \leq d(x, z)$$

1. Define

- ▶  $S \stackrel{\text{def}}{=} \{x, y, z\} \subseteq M$  metric space with just 3 points;
- ▶ Isometry  $f: S \rightarrow \mathbb{R}_\infty^3$

$$f(p) \stackrel{\text{def}}{=} (d(p, x), d(p, y), d(p, z)).$$

2. Obtain the equivalent analytical problem

$$\left| \max(d(x, y), |d(x, z) - d(y, z)|) \right. \\ \left. - \max(d(y, z), |d(x, y) - d(x, z)|) \right| \leq \\ \max(d(x, z), |d(x, y) - d(y, z)|)$$

3. Prove the above inequality using Fourier-Motkin elimination.

Thank you for your attention!

## Bibliography

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