

Controlling Polyvariance for Specialization-Based Verification

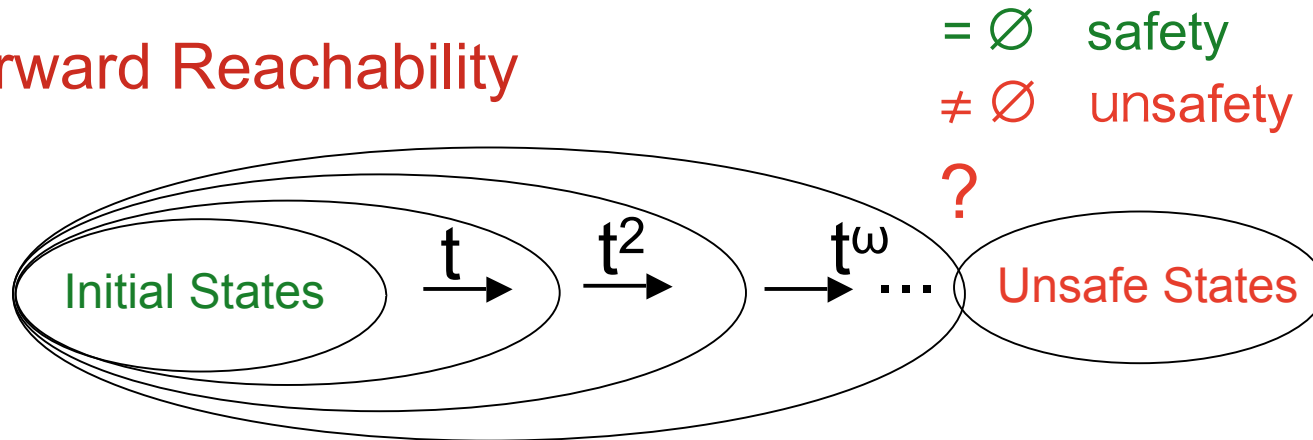
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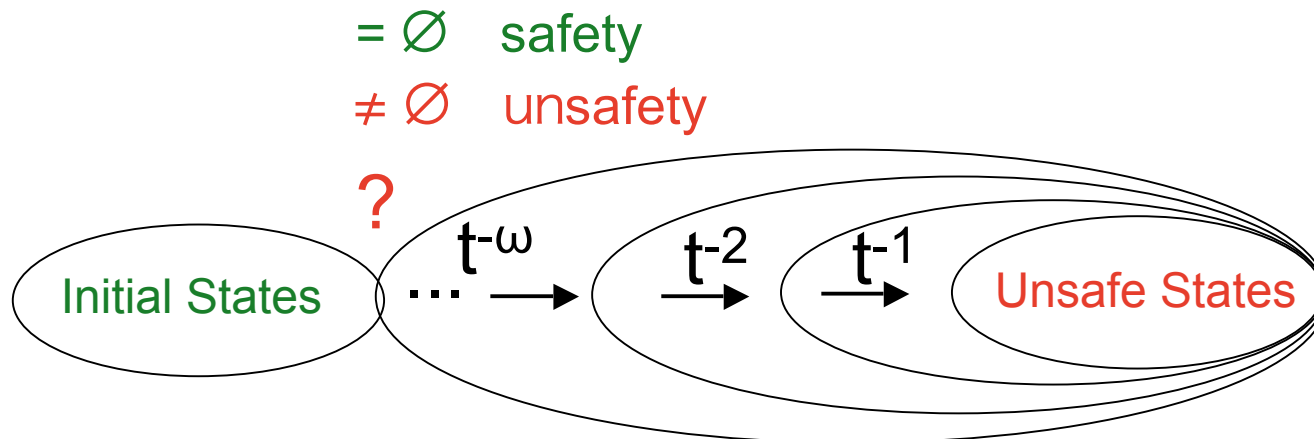
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Verification via Reachability

Forward Reachability



Backward Reachability



Backward Reachability as a Constraint Logic Program

Bw:

(I's) $\text{unsafe} \leftarrow \text{init}_1(X) \wedge \text{bwReach}(X)$

⋮

(T's) $\text{bwReach}(X) \leftarrow t_1(X, X') \wedge \text{bwReach}(X')$

⋮

(U's) $\text{bwReach}(X) \leftarrow u_1(X)$

⋮

Theorem:

The system is safe iff $\text{unsafe} \notin M(\text{Bw})$

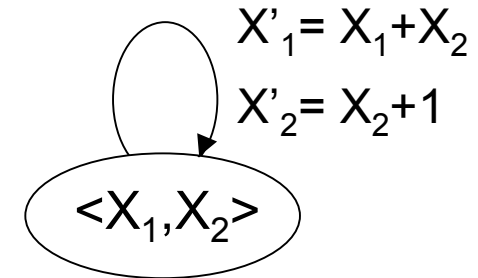
$A \vartheta$

$\simeq (S_{\text{Bw}})^\omega$

$A \leftarrow c$ with $c \vartheta$ satisf.

An Example of System Verification

$$\left[\begin{array}{l} \text{init}(\langle X_1, X_2 \rangle): X_1 \geq 1 \wedge X_2 = 0 \\ \text{t}(\langle X_1, X_2 \rangle, \langle X'_1, X'_2 \rangle): X'_1 = X_1 + X_2 \wedge X'_2 = X_2 + 1 \\ \text{u}(\langle X_1, X_2 \rangle): X_2 > X_1 \end{array} \right.$$



Bw:

1. $\text{unsafe} \leftarrow X_1 \geq 1 \wedge X_2 = 0 \wedge \text{bwReach}(X_1, X_2)$
2. $\text{bwReach}(X_1, X_2) \leftarrow X'_1 = X_1 + X_2 \wedge X'_2 = X_2 + 1 \wedge \text{bwReach}(X'_1, X'_2)$
3. $\text{bwReach}(X_1, X_2) \leftarrow X_2 > X_1$

Unfortunately, the computation of $M(\text{Bw})$ does not terminate.

Verification via Specialization:

- (A) $\text{Bw} \longrightarrow \text{SpBw}$
- (B) $\text{unsafe} \notin M(\text{SpBw})$

Specialization via Unfold/Definition/Fold

def-intro:

$$4. \text{ new1}(X_1, X_2) \leftarrow \underline{X_1 \geq 1 \wedge X_2 = 0 \wedge \text{bwReach}(X_1, X_2)} \quad \blacksquare \ 0$$

fold:

$$1f. \text{ unsafe} \leftarrow X_1 \geq 1 \wedge X_2 = 0 \wedge \text{new1}(X_1, X_2)$$

unfold:

$$4u. \text{ new1}(X_1, X_2) \leftarrow \underline{X_1 \geq 1 \wedge X_2 = 0 \wedge X'_1 = X_1 \wedge X'_2 = 1 \wedge \text{bwReach}(X'_1, X'_2)}$$

def-intro:

$$\text{newp}(X'_1, X'_2) \leftarrow \underline{X'_1 \geq 1 \wedge X'_2 = 1 \wedge \text{bwReach}(X'_1, X'_2)} \quad \blacksquare \ 1$$

fold: ...

unfold: ...

def-intro:

$$\text{newq}(X''_1, X''_2) \leftarrow \underline{X''_1 \geq 1 \wedge X''_2 = 2 \wedge \text{bwReach}(X''_1, X''_2)} \quad \blacksquare \ 2$$

⋮

⋮

■ Nontermination of specialization

Need for Generalization

def-intro:

5. $\text{new2}(X_1, X_2) \leftarrow X_1 \geq 1 \wedge X_2 \geq 0 \wedge \text{bwReach}(X_1, X_2)$ (generalization)

4uf. $\text{new1}(X_1, X_2) \leftarrow X_1 \geq 1 \wedge X_2 = 0 \wedge X'_1 \geq X_1 \wedge X'_2 = 1 \wedge \text{new2}(X'_1, X'_2)$

From 5 by unfold-fold:

6. $\text{new2}(X_1, X_2) \leftarrow X_1 \geq 1 \wedge X_2 \geq 0 \wedge X'_1 = X_1 + X_2 \wedge X'_2 = X_2 + 1 \wedge \text{new2}(X'_1, X'_2)$

7. $\text{new2}(X_1, X_2) \leftarrow X_1 \geq 1 \wedge X_2 > X_1$

SpBw: 1f, 4uf, 6, 7.

-
- Specialization has terminated (due to generalization).
 - The computation of $M(\text{SpBw})$ terminates:

↑ $\text{unsafe} \notin M(\text{SpBw})$

$\text{new1}(X_1, X_2) \leftarrow \text{false}$

$\text{new2}(X_1, X_2) \leftarrow X_1 \geq 1 \wedge X_2 > 1$

A Different Specialization

new2 is *more general* than *new1*: use *new2*, instead of *new1*.

SpBw1:

1f'. *unsafe* $\leftarrow X_1 \geq 1 \wedge X_2 = 0 \wedge \text{new2}(X_1, X_2)$

6. *new2*(X_1, X_2) $\leftarrow X_1 \geq 1 \wedge X_2 \geq 0 \wedge X'_1 = X_1 + X_2 \wedge X'_2 = X_2 + 1 \wedge \text{new2}(X_1, X_2)$

7. *new2*(X_1, X_2) $\leftarrow X_1 \geq 1 \wedge X_2 > X_1$

SpBw1: 1f, 6, 7.

- Fold “immediately”: use of *new1* and *new2*.

More polyvariance (SpBw).

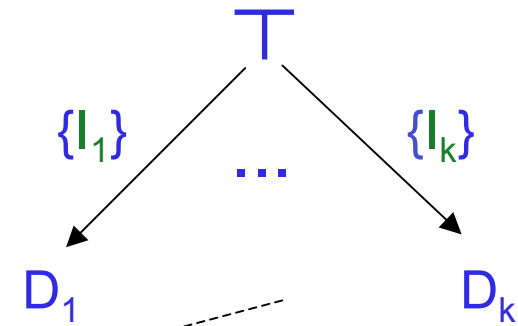
- Fold at the end “with a maximally general definition”: use of *new2* only.

Less polyvariance (SpBw1).

Polyvariance depends on generalization and folding and affects the specialization time and the size of the specialized program (and thus, the computation of the $M(\text{SpBw})$).

Constructing the Definition Tree: DefsTree

Initialization:

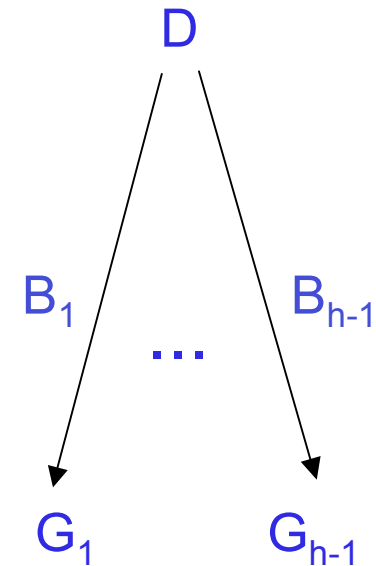
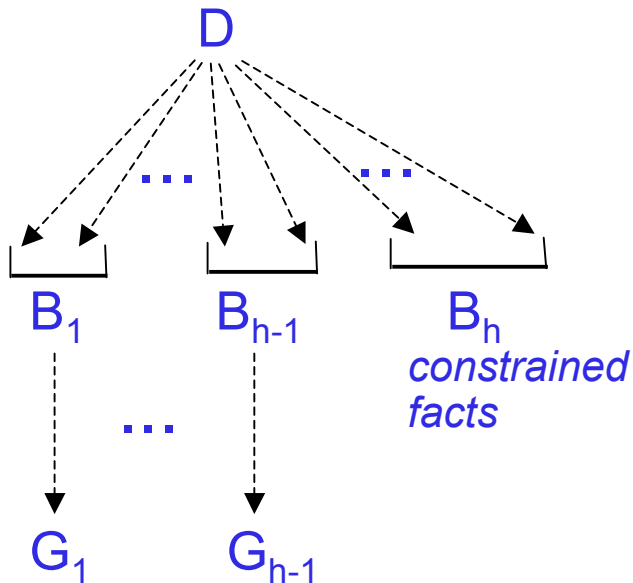


a generic node D :

Unfold using T 's and U 's:

Partition of clauses into blocks:

Generalize:



- Stop if node D occurs earlier in DefsTree.

DefsTree for Our Verification

Initialization:

T

{1}

$D_1: 4. \text{new1}(X_1, X_2) \leftarrow \underline{X_1 \geq 1 \wedge X_2 = 0} \wedge \text{bwReach}(X_1, X_2)$

{4u}

$D_2: 5. \text{new2}(X_1, X_2) \leftarrow X_1 \geq 1 \wedge X_2 \geq 0 \wedge \text{bwReach}(X_1, X_2)$

Unfold:

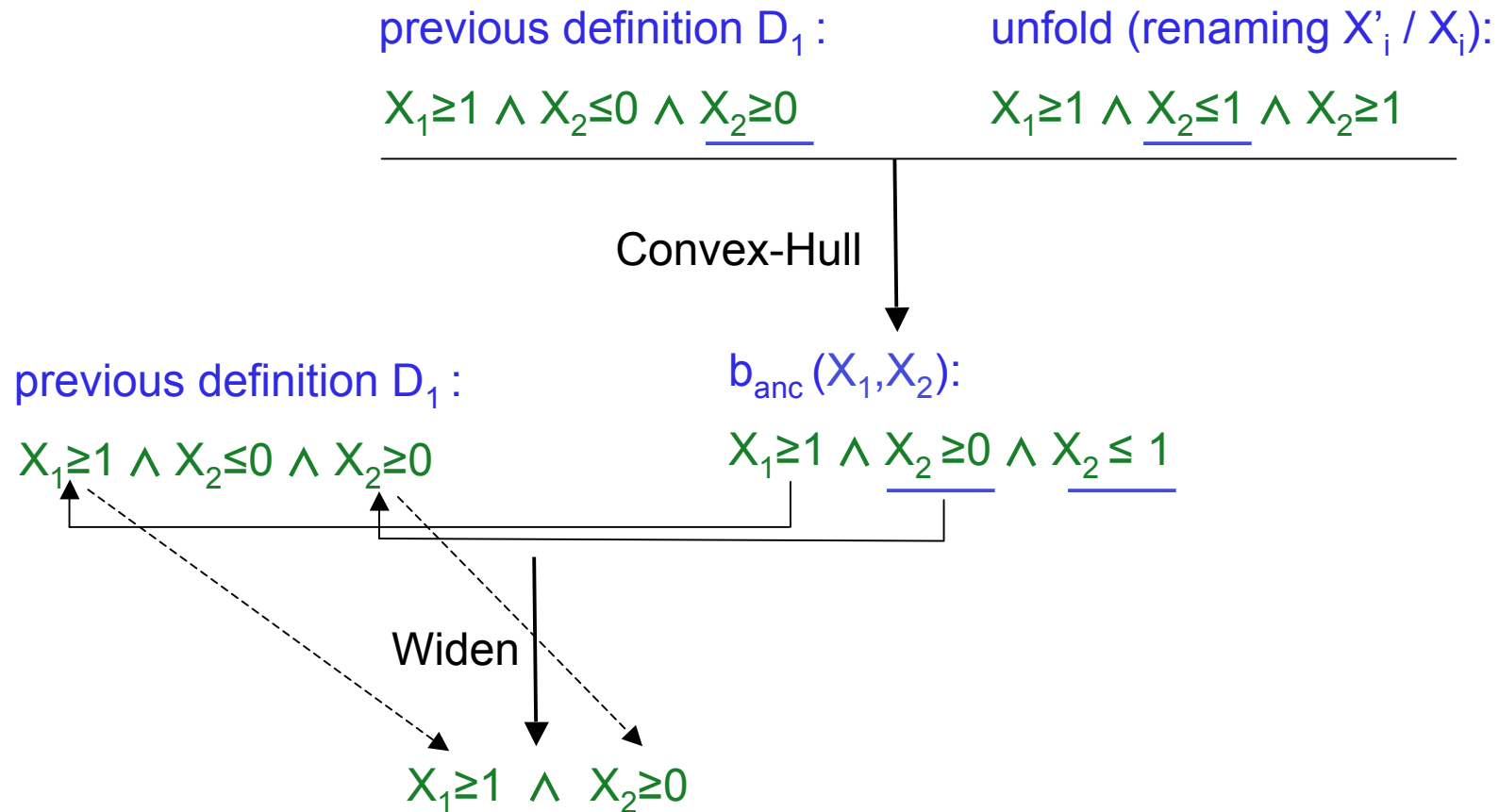
$4u. \text{new1}(X_1, X_2) \leftarrow X_1 \geq 1 \wedge X_2 = 0 \wedge \underline{X'_1 = X_1 \wedge X'_2 = 1} \wedge \text{bwReach}(X'_1, X'_2)$

Generalize (ch+widen):

$5. \text{new2}(X_1, X_2) \leftarrow \underline{X_1 \geq 1 \wedge X_2 \geq 0} \wedge \text{bwReach}(X_1, X_2)$

D_1

Generalization: (Convex-Hull and) Widen



Another generalization operator: (Convex-Hull and) WidenSum.

It takes into account the coefficients of the variables (in our case: 1).

Generic Specialization Algorithm

Input: program Bw

Output: program SpBw such that $\text{unsafe} \in M(\text{Bw})$ iff $\text{unsafe} \in M(\text{SpBw})$

Initialization: $\text{DefsTree} := \{T \rightarrow D_1, \dots, T \rightarrow D_k\}$

while there exists a definition D in DefsTree which does not occur earlier

do - unfold using T_i 's and U_i 's and derive UnfD;

- definition introduction:

$\text{Partition}(\text{UnfD}, \{B_1, \dots, B_h\})$;

$\text{Generalize}(D, B_i, \text{DefsTree}, G_i)$ and derive a new DefsTree

od

$\text{Fold}(\text{DefsTree}, \text{SpBw})$

blocks

a generalized definition

Various Partition Operators

UnfD: clauses $C_1, \dots, C_m, \underline{C_{m+1}, \dots, C_n}$
(constrained facts)

Partition:

1. Singleton: $\underline{\{C_1\}}, \dots, \underline{\{C_m\}}$
(m blocks)

2. Finite Domain: clauses C_i and C_j in the same block iff $\text{con}(C_i)|_{X'} \simeq_{\text{fd}} \text{con}(C_j)|_{X'}$

e.g., $X'_1=a \wedge X'_2=a \simeq_{\text{fd}} X'_1=a \wedge X'_2=X'_1$

3. All: $\underline{\{C_1, \dots, C_m\}}$
(one block)

⋮

Reconstructing Known Techniques

Technique by

	Partition	Generalization	Folding
Cousot-Halbwachs:	Finite-Domain	Widen	
Peralta-Gallagher:	All	Widen	Maximally General
FPPS (Lopstr 2010):	Singleton	Widen (or WidenSum)	Immediate
our <i>new1-new2</i> :	Singleton	Widen	Immediate
our <i>new2</i> :	Singleton	Widen	Maximally General

Verification of System: Backward Reachability

	No-Specializat.		All_Widen	Singleton_WidenSum	
Bakery 4	130	Im	19 (6)	101 (1745)	← Times in milliseconds. Number of definitions between parentheses.
		MG	19 (6)	77 (1172)	
Ticket 2	∞	Im	∞	0.02 (11)	← ∞ means more than 200 seconds
		MG	∞	0.02 (11)	
Futurebus+	15	Im	17 (6)	2.4 (19)	
		MG	15 (3)	2.2 (15)	
McCarthy91	∞	Im	4.13 (5)	∞	
⋮		MG	4.12 (3)	∞	
29 protocols:	20 verified	MG	21 verified	27 verified	

■ Similar results for Forward Reachability.

Conclusions

- A generic specialization algorithm reconstructing various techniques known in the literature (plus new ones), depending on:
 - partition operators (singleton, all, ...)
 - generalization operators (widen, ...)
 - folding procedure (immediate, maximally general)
- Specialization improves precision (i.e., the number of verified properties or systems) but may increment verification time
- Polyvariance control may allow fewer definitions and shorter verification times at the expense of possible loss of precision.

Tool

An implementation in SICStus Prolog as a module of the MAP transformation system.

<http://map.uniroma2.it/mapweb>

The screenshot displays the MAP web interface, titled "MAP - Specialization-Based Reachability Analysis of Infinite-State Transition Systems". The interface is divided into four main sections: 1. Program Uploading, 2. Options Selection, 3. Specialization, and 4. Perfect Model. The "Specialization" section is currently active, showing a text area with Prolog code and a configuration panel on the right.

1. Program Uploading

```
% Bakery Protocol 2 processes - safety [Delzanno-Podelski,2001]
%
% Transitions
t(s(t,A,S,B),s(w,D,S,B)) :- D:=B+1, A>=0, B>=0.
t(s(w,A,S,B),s(u,A,S,B)) :- A<B, A>=0.
t(s(w,A,S,B),s(u,A,S,B)) :- B:=0, A>=0.
t(s(u,A,S,B),s(t,D,S,B)) :- D:=0, A>=0, B>=0.
t(s(S,A,t,B),s(S,A,w,D)) :- D:=A+1, A>=0.
t(s(S,A,w,B),s(S,A,u,B)) :- B<A, B>=0.
t(s(S,A,w,B),s(S,A,u,B)) :- A:=0, B>=0.
t(s(S,A,u,B),s(S,A,t,D)) :- D:=0, B>=0, A>=0.

% Elementary Properties
elem(s(u,A,u,B),unsafe) :- A>=0, B>=0.
elem(s(t,A,t,C),initial) :- A:=0, C:=0.
%elem(s(w,A,w,A),initial):- A>0.

% Temporal Properties
inv1 :- unreachable(backward,initial,unsafe).
```

Specialization Options:

- Invariant: inv1
- Timeout: 10 s
- Default Custom

Generalization Parameters:

- MaxCoeff: off
- Firing Relation: variant
- Gen. Oper.: widen
- Gen. Param.: e_leq_maxsum

Polyvariance Parameters:

- Partitioning: single
- Include Foldable: include
- Candidate: w.r.t. ancestor
- Post-Folding: most general

Specialize Help

Future Work

- Perform more system verifications and check scalability of the approach.
- Use of polyvariance control outside the scope of the verification of reactive systems.

References

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