

Winning CARET Games with Modular Strategies

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- In this work we focus on **pushdown systems**
- They can model systems with potentially recursive procedure calls, as:
 - control flows in programs of sequential imperative and object oriented programming languages
 - distributed architectures
 - communication protocols
- In an open pushdown system, some of the choices depend upon the controllable inputs and some represent uncontrollable nondeterminism (as a two-players game)

Recursive Game Graphs

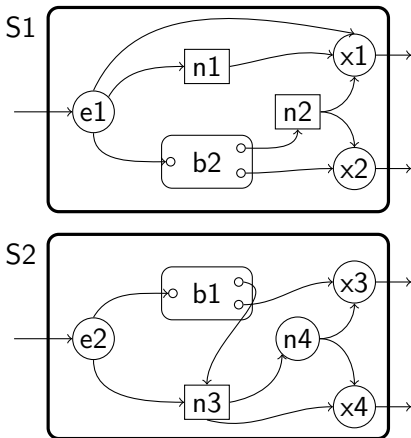
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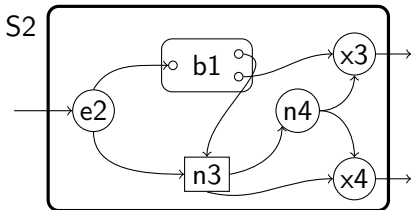
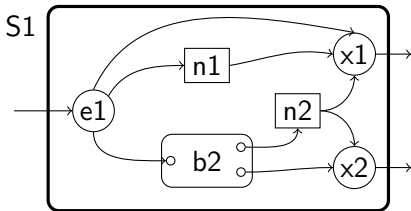


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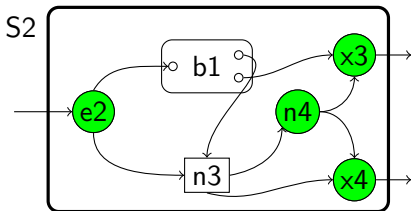
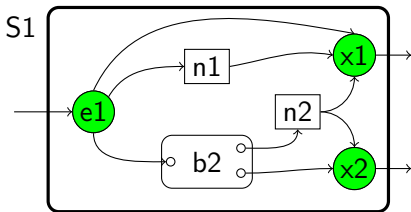


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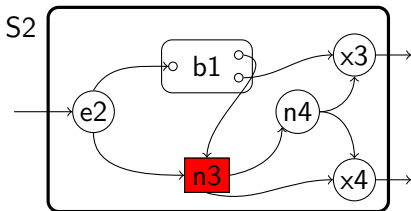
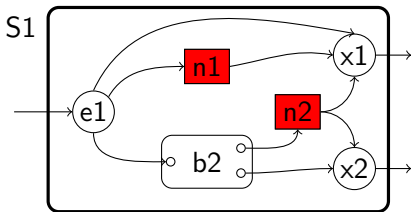


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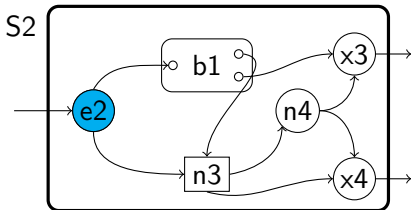
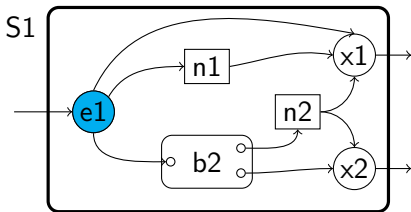


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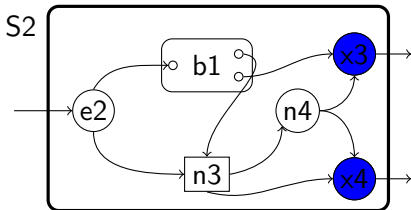
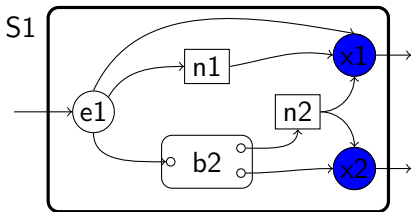


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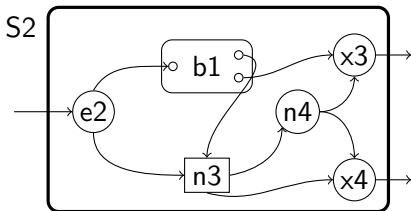
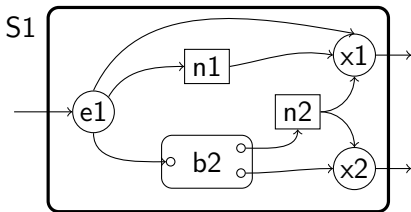
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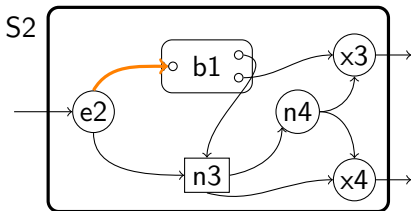
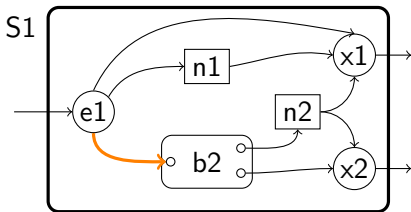
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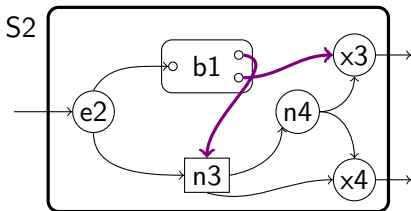
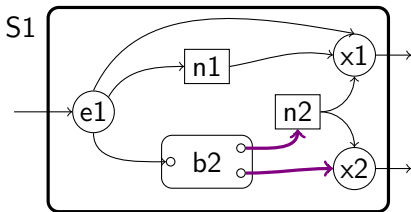
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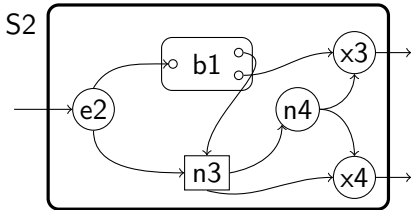
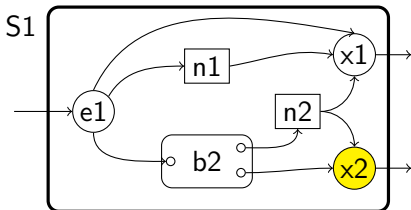
Recursive Game Graphs

A *play* of an RGG is a sequence of vertices starting from an entry node of the start module and from a node to its successor there is a permitted transition

- A *winning set* over an RGG is a language on the alphabet of the RGG
- A winning set can be expressed by a winning condition (automata, formulas, etc...)
- A play is said to be *winning* if its labeling is a string that belongs to the winning set

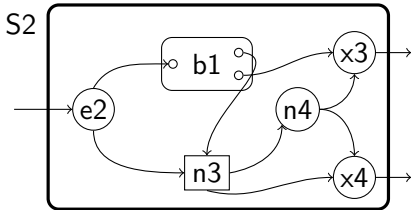
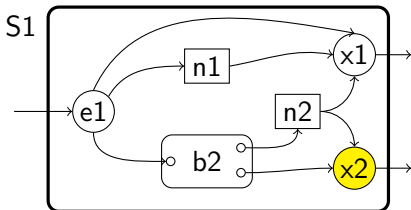
- A *strategy* for a player is a function that encodes how the player must play the game. It associates a move to every run that ends in a node controlled by that player
- A strategy is *winning* for a player if all plays according with that strategy are winning, whatever are the moves of the other player
- On RGGs can be defined a specific type of strategy, called **modular**
- A strategy is said modular iff it can only refer to the *local memory* of the module to choose the next move

We consider a reachability condition on x_2



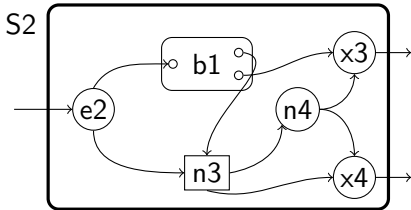
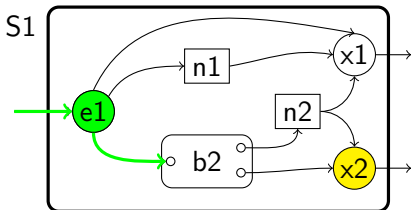
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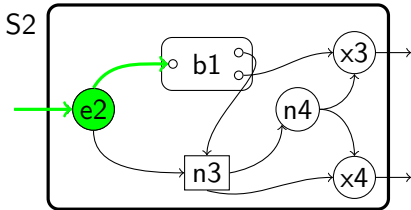
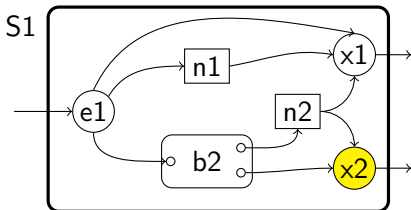
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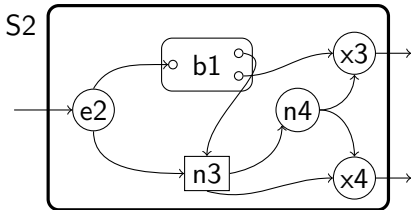
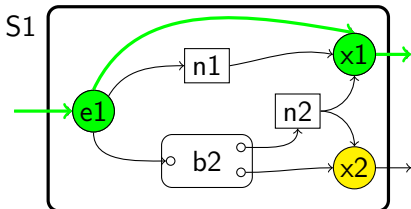
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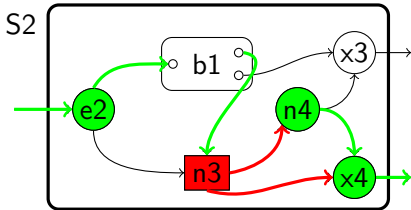
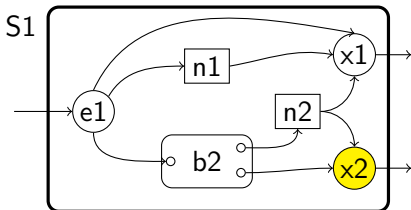
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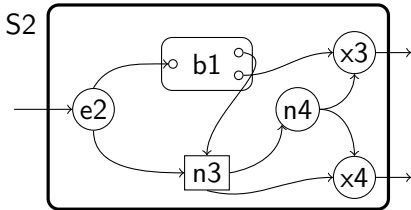
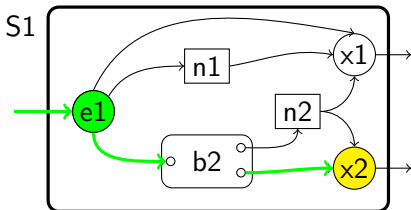
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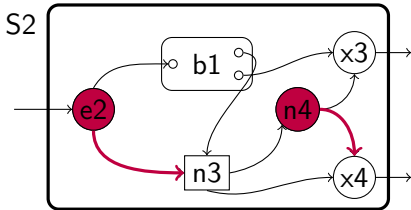
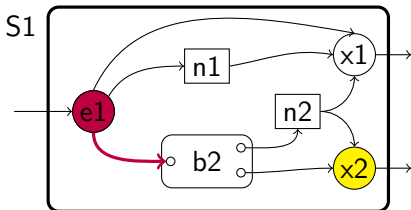
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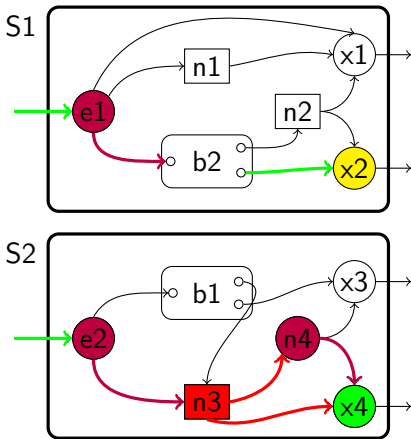
- The strategy seen before is not modular. because the third rule must know informations of the previous module to choose the internal move to e_1 or the call to b_2
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Studying games on graphs allows to analyze behaviours of *open systems*

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If a winning modular strategy can be found, it means that we can design for every module a controller that guarantees the correctness of the system **whatever is the context in which the module is invoked**

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Problem

Given a RGG G and a winning condition, is there a modular winning strategy for the GreenPlayer?

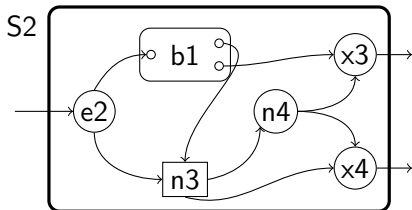
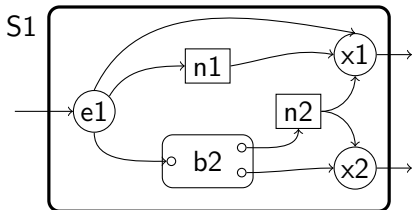
In this work we analyze and resolve the problem for
a new class of games that we have defined
Modular CARET Games

- CARET is a temporal logic designed for recursive machines
- Allows to express also stack inspection properties and specifications of partial and total correctness with respect to pre and post conditions
- The syntax is:

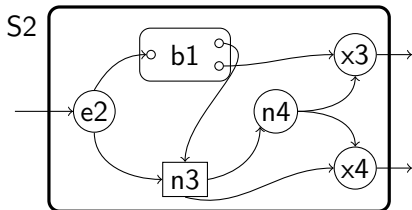
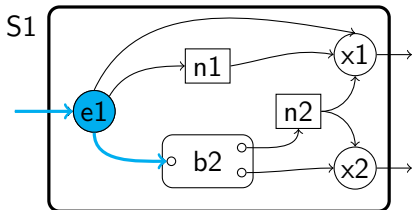
$$\varphi := p \mid \varphi \vee \varphi \mid \neg \varphi \mid \bigcirc^g \varphi \mid \bigcirc^a \varphi \mid \bigcirc^- \varphi \mid \varphi \mathcal{U}^g \varphi \mid \varphi \mathcal{U}^a \varphi \mid \varphi \mathcal{U}^- \varphi$$

- Temporal operators are defined in three different **modalities**:
 - **Global successor**
 - **Abstract successor**
 - **Caller**

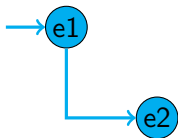
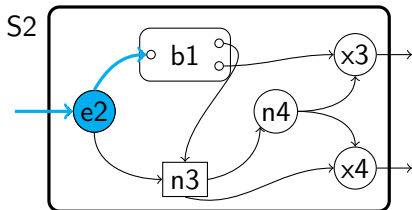
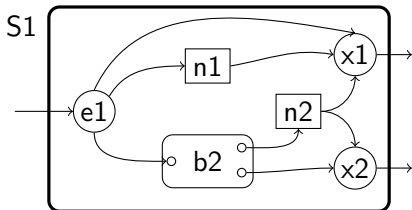
Differences between modalities



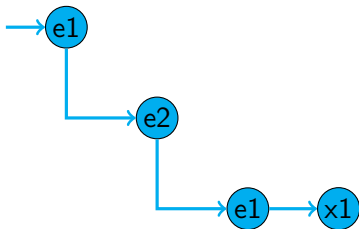
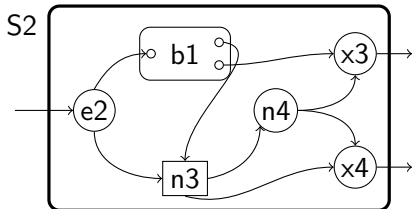
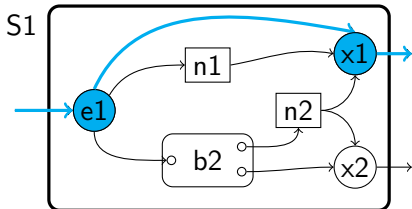
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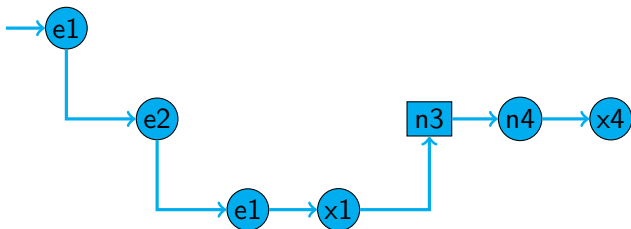
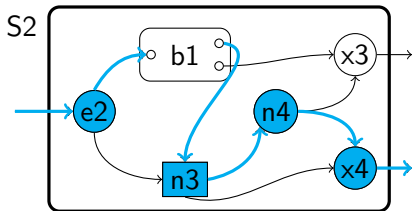
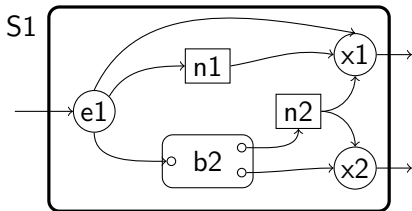
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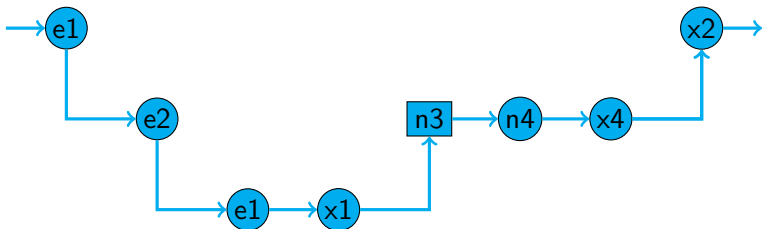
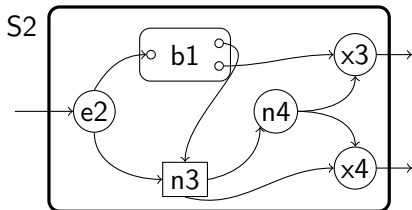
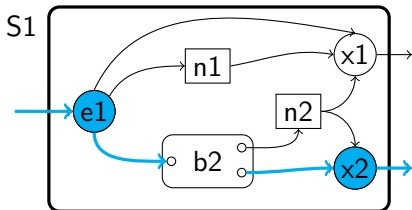
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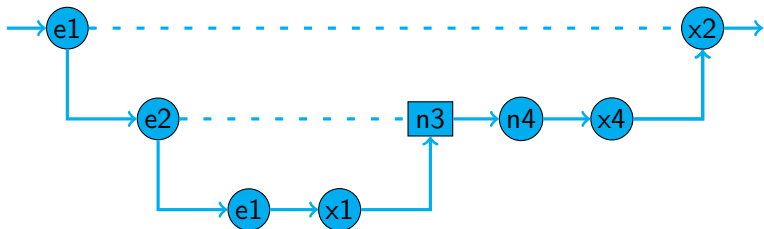
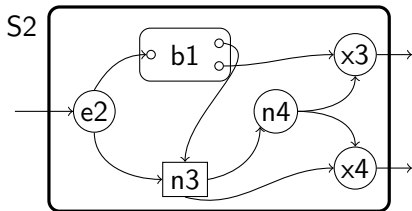
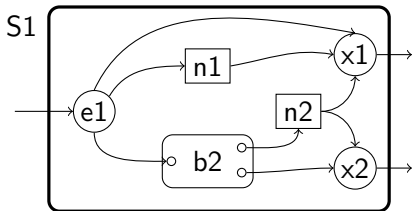
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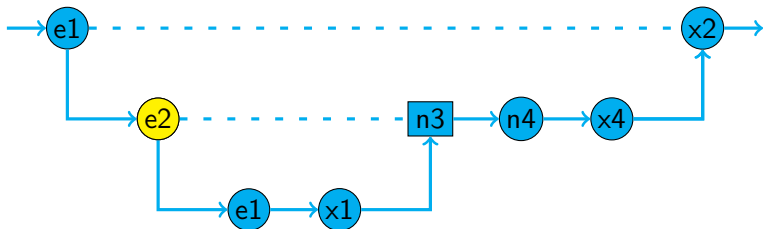
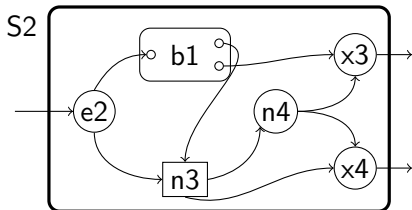
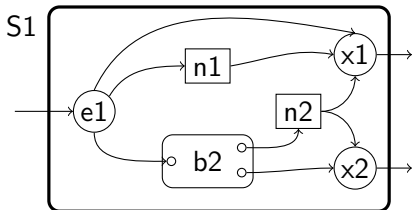
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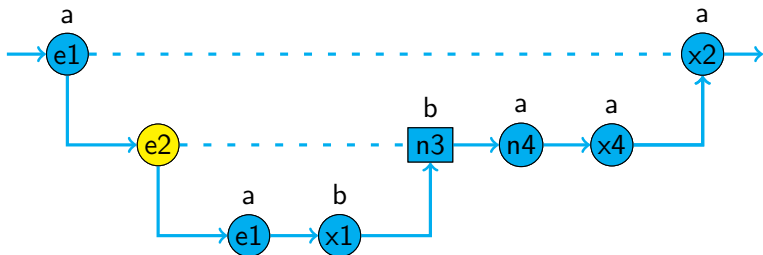
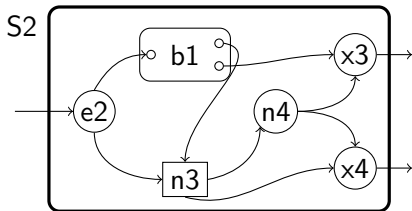
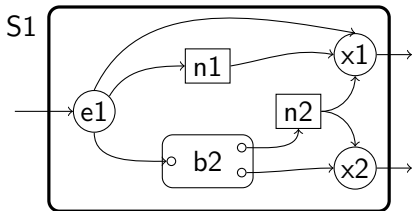
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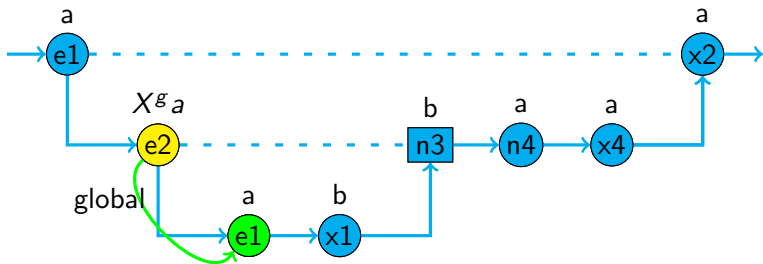
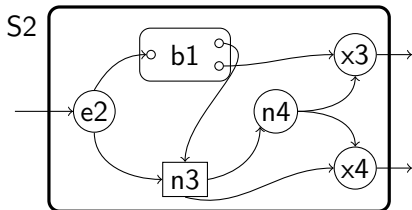
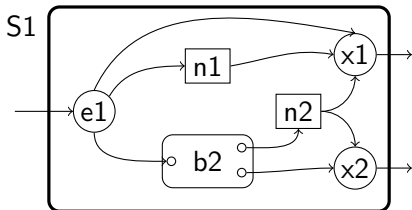
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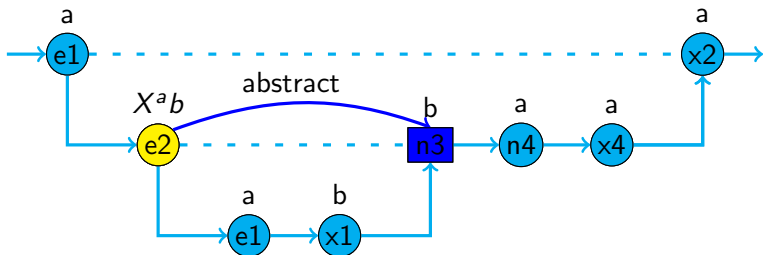
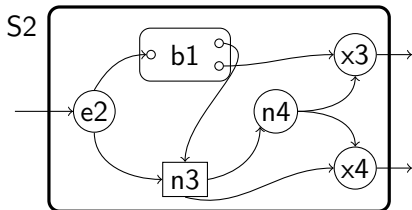
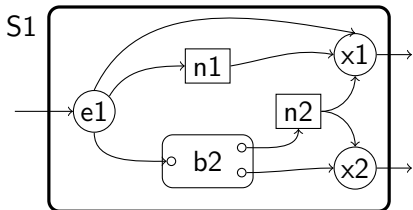
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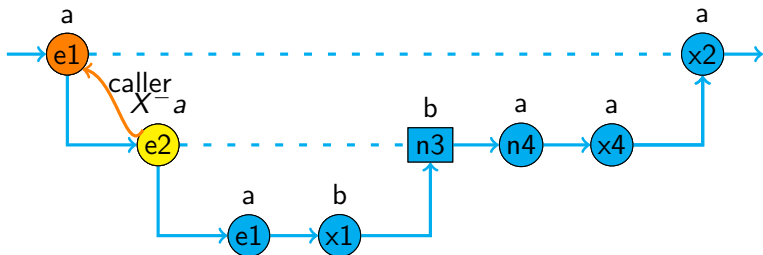
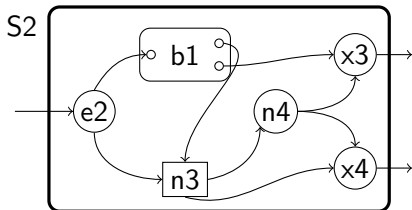
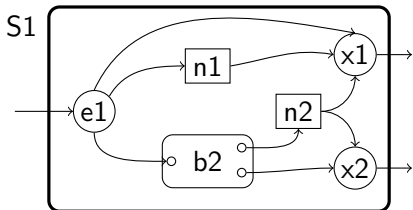
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- We show that deciding the existence of a winning modular strategy in a CARET game is 2EXPTIME -Complete
- The lower bound derives from the fact that LTL-games for not recursive graph are already 2EXPTIME -Hard
- We'll show only that the upper bound of the proposed construction is 2EXPTIME

Idea

Reduce the decision problem to a problem of emptiness of nondeterministic automata with parity condition

Let $\langle G, \varphi \rangle$ be a modular CARET game

- Constructing an equivalent game $\langle G', color \rangle$ with a parity winning condition such that $|G'| = O(2^{|\varphi|})$
- Constructing from $\langle G', color \rangle$ a two-way alternating parity tree automaton A_{win} that accepts a strategy iff corresponds to a winning modular strategy
- Convert A_{win} in a one-way nondeterministic automaton, take its intersection with the tree automaton that accepts strategy trees and check the emptiness of this resulting automaton

- Deciding existence of modular winning strategies is solved in [Alur, La Torre, Madhusudan, 2003] for:
 - Reachability and safety winning condition (*finite plays*)
 - External winning condition given as deterministic/universal Büchi/coBüchi or LTL formulas (*infinite plays*)
- As far as we know, studies that analyze the problem with non-regular winning condition are not known
- Our work extends the previous results to this class of winning conditions, because CARET formulas can express also not regular properties

- The implementability of the proposed technique in tools, however, is countered by the high complexity, exponential in the size of the graph and doubly exponential in the size of the formula
- Typically, the analysis of real systems are done for small formulas
- Regarding the structural complexity, deciding the existence of modular strategies for LTL games is NP-complete
- In this paper we have not analyzed the structural complexity and the question remains open